

MCHE 513: Intermediate Dynamics

Fall 2018 – Homework 4

Assigned: Thursday, October 18th

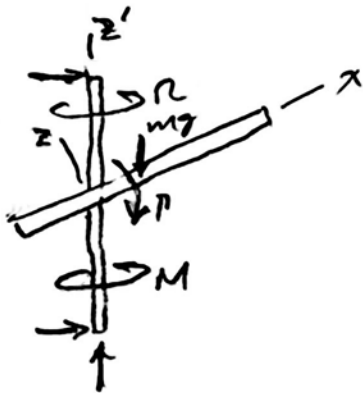
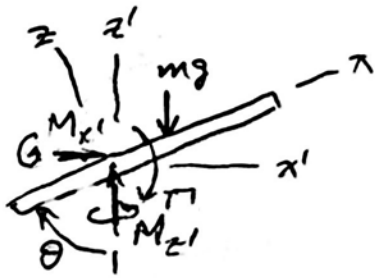
Due: Friday, October 26th, 5pm

Assignment: From “Engineering Dynamics” by Jerry Ginsberg, problems:
6.12, 6.13, 6.32, 6.41

Submission: Emailed *single* pdf document:

- to joshua.vaughan@louisiana.edu
- with subject line and filename ULID-MCHE513-HW4, where ULID is your ULID
- *Note:* Submissions with incorrect filenames or submitted as multiple images/pdfs will be rejected.

Exercise 6.12



Given $\theta = \frac{\pi}{2} \sin(\omega t)$, constant Ω .

Find Π and M at $\theta = \frac{\pi}{2}$ and $\pi/3$.

Solution: Consider the isolated bar to find Π , then the bar on the shaft to find M .

$$I_{xx} = 0, I_{yy} = I_{zz} = \frac{1}{12} mL^2 + m\left(\frac{L}{2}\right)^2$$

$$\bar{\omega} = \Omega \bar{k}' + \dot{\theta} \bar{j}, \quad \bar{\alpha} = \ddot{\theta} \bar{j} + \Omega \dot{\theta} (\bar{k}' \times \bar{j})$$

$$\text{Set } \bar{k}' = \cos\theta \bar{i} + \sin\theta \bar{k}$$

$$\bar{\omega} = \Omega \cos\theta \bar{i} + \dot{\theta} \bar{j} + \Omega \sin\theta \bar{k}$$

$$\bar{\alpha} = \Omega \dot{\theta} (-\sin\theta \bar{i} + \cos\theta \bar{k}) + \ddot{\theta} \bar{j}$$

Isolated bar: $\sum \bar{M}_c \cdot \bar{j} = mg\left(\frac{L}{2} \sin\theta\right) + \Pi = \dot{H}_c \cdot \bar{j}$

Assembly: $\sum \bar{M}_c \cdot \bar{k}' = M$ but $\bar{k}' = \cos\theta \bar{i} + \sin\theta \bar{k}$

so $M = \dot{H}_c \cdot (\cos\theta \bar{i} + \sin\theta \bar{k})$

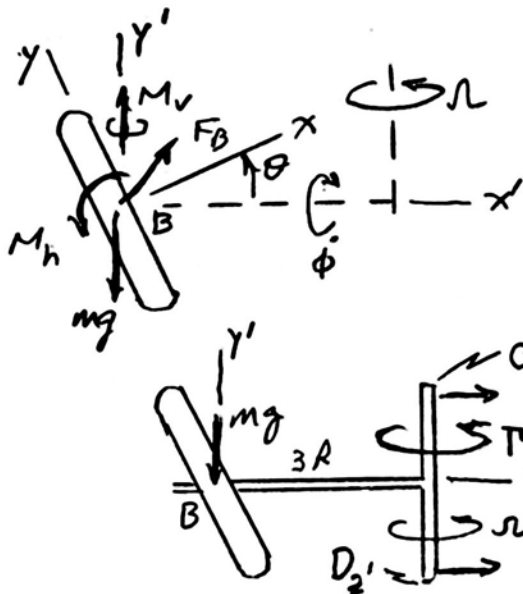
$$\bar{H}_c = \frac{1}{9} mL^2 (\dot{\theta} \bar{j} + \Omega \sin\theta \bar{k}), \quad \frac{\partial \bar{H}_c}{\partial t} = \frac{1}{9} mL^2 (\ddot{\theta} \bar{j} + \Omega \dot{\theta} \cos\theta \bar{k})$$

$$\dot{\bar{H}}_c = \frac{\partial \bar{H}_c}{\partial t} + \bar{\omega} \times \bar{H}_c = \frac{1}{9} mL^2 [\ddot{\theta} - \Omega^2 \sin\theta \cos\theta] \bar{j} + \frac{2}{9} mL^2 \Omega \dot{\theta} \cos\theta \bar{k}$$

so $\Pi = \frac{1}{9} mL^2 (\ddot{\theta} - \Omega^2 \sin\theta \cos\theta)$ Δ

$M = \frac{2}{9} mL^2 \Omega \dot{\theta} \sin\theta \cos\theta$ Δ

Exercise 6.13



Given constant Ω , $\phi = 0$
in illustrated position.

Find equation of motion
for ϕ and an expression for Π .

Solution: Because the
mass of the T-bar is zero,
it can be included in the
free body diagram of the disk

In the FBD of the isolated disk, M_v & M_h are couple
reactions exerted by the shaft. These are internal for
the FBD of the assembly.

Attach xyz to the disk and $x'y'z'$ to the shaft.

Transformation: starting from $x'y'z'$, rotate by $+\theta$
about z' , then $-\phi$ about $x' \Rightarrow$ body-fixed, so

$$[xyz]^T = [R][x'y'z']^T, [R] = [R_z(\theta)][R_x(-\phi)]$$

$$[R] = \begin{bmatrix} \cos\theta & \sin\theta & 0 \\ -\sin\theta & \cos\theta & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & \cos\phi & -\sin\phi \\ 0 & \sin\phi & \cos\phi \end{bmatrix}$$

$$\text{Then } \bar{\omega} = \Omega \bar{j}' - \dot{\phi} \bar{i}', \bar{\alpha} = -\ddot{\phi} \bar{i}' - \dot{\phi}(\Omega \bar{j}' \times \bar{i}') = -\ddot{\phi} \bar{i}' + \Omega \dot{\phi} \bar{k}'$$

Convert to xyz components:

$$\begin{Bmatrix} \omega_x \\ \omega_y \\ \omega_z \end{Bmatrix} = [R] \begin{Bmatrix} -\dot{\phi} \\ \Omega \\ 0 \end{Bmatrix} = \begin{Bmatrix} \Omega \cos\phi \sin\theta - \dot{\phi} \cos\theta \\ \Omega \cos\phi \cos\theta + \dot{\phi} \sin\theta \\ \Omega \sin\phi \end{Bmatrix}$$

$$\begin{Bmatrix} \alpha_x \\ \alpha_y \\ \alpha_z \end{Bmatrix} = [R] \begin{Bmatrix} -\ddot{\phi} \\ 0 \\ \Omega \dot{\phi} \end{Bmatrix} = \begin{Bmatrix} -\ddot{\phi} \cos\theta - \Omega \dot{\phi} \sin\phi \sin\theta \\ \ddot{\phi} \sin\theta - \Omega \dot{\phi} \sin\phi \cos\theta \\ \Omega \dot{\phi} \cos\phi \end{Bmatrix}$$

$$I_{xx} = \frac{1}{2} mR^2, I_{yy} = I_{zz} = \frac{1}{4} mR^2$$

Exercise 6.13 (cont.)

$$\begin{aligned} \{\dot{H}_B\} &= [I]\{\alpha\} + \{\omega\} \otimes [I]\{\omega\} \\ &= \frac{1}{4} m R^2 \left\{ \begin{array}{l} 2\ddot{\phi} \cos \theta + \Omega \dot{\phi} \sin \phi \sin \theta \\ \ddot{\phi} \sin \theta + \Omega^2 \sin \phi \cos \phi \sin \theta - 2\Omega \dot{\phi} \sin \phi \cos \theta \\ \cos \theta [\dot{\phi}^2 \sin \theta - \Omega^2 (\cos \phi)^2 \sin \theta + 2\Omega \dot{\phi} \omega \sin \phi \cos \theta] \end{array} \right\} \end{aligned}$$

From the FBD of the isolated disk

$$\Sigma \bar{M}_B \cdot \bar{c}' = 0 = \dot{H}_B \cdot \bar{c}'$$

From the FBD of the assembly

$$\Sigma \bar{M}_O \cdot \bar{j}' = \Gamma - (C_{z'} + D_{z'}) 3R = \dot{H}_B \cdot \bar{j}'$$

but $\Sigma \bar{F} = m \bar{a}_B$ with $\bar{a}_B = (3R)\Omega^2 \bar{c}'$

so $\Sigma \bar{F} \cdot \bar{k}' = C_{z'} + D_{z'} = 0 \Rightarrow \Gamma = \dot{H}_B \cdot \bar{j}'$

Use $[R]$ to obtain components.

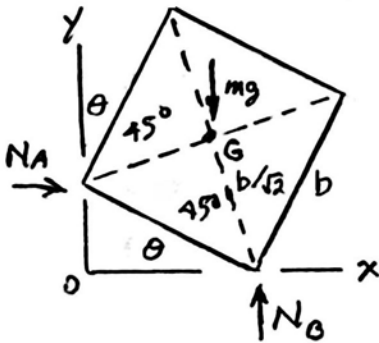
$$\left\{ \begin{array}{l} \dot{H}_B \cdot \bar{c}' \\ \dot{H}_B \cdot \bar{j}' \\ \dot{H}_B \cdot \bar{k}' \end{array} \right\} = [R]^T \{\dot{H}_B\} = \left\{ \begin{array}{l} 0 \\ \Gamma \\ ? \end{array} \right\}$$

Carry out:

$$\ddot{\phi} [1 + (\cos \theta)^2] + \Omega^2 \sin \theta \cos \theta (\sin \phi)^2 = 0 \quad \triangleleft$$

$$\Gamma = -\frac{1}{4} m R^3 \left[(\dot{\phi} \cos \phi - \dot{\phi}^2 \sin \phi) \sin \theta \cos \theta - 2\Omega \dot{\phi} \sin \phi \cos \phi (\sin \theta)^2 \right] \quad \triangleleft$$

Exercise 6.32



Find diff eq for θ , and N_A & N_B .

Solution: First describe \bar{a}_G :

$$\bar{r}_{G/O} = \frac{b}{\sqrt{2}} \sin\left(\theta + \frac{\pi}{4}\right) (\bar{i} + \bar{j})$$

$$\bar{v}_G = \dot{\bar{r}}_{G/O} = \frac{b}{\sqrt{2}} \dot{\theta} \cos\left(\theta + \frac{\pi}{4}\right) (\bar{i} + \bar{j})$$

$$\bar{a}_G = \dot{\bar{v}}_G = \frac{b}{\sqrt{2}} \left[\ddot{\theta} \cos\left(\theta + \frac{\pi}{4}\right) - \dot{\theta}^2 \sin\left(\theta + \frac{\pi}{4}\right) \right] (\bar{i} + \bar{j})$$

Then $\Sigma \bar{F} \cdot \bar{i} = N_A = m \bar{a}_G \cdot \bar{i}$, $\Sigma \bar{F} \cdot \bar{j} = N_B - mg = m \bar{a}_G \cdot \bar{j}$

$$\Sigma \bar{M}_G \cdot \bar{k} = N_A \frac{b}{\sqrt{2}} \cos\left(\theta + \frac{\pi}{4}\right) + N_B \frac{b}{\sqrt{2}} \cos\left(\theta + \frac{\pi}{4}\right) = \frac{1}{6} m b^2 (-\ddot{\theta})$$

Thus $N_A = \frac{1}{\sqrt{2}} m b \left[\ddot{\theta} \cos\left(\theta + \frac{\pi}{4}\right) - \dot{\theta}^2 \sin\left(\theta + \frac{\pi}{4}\right) \right]$ ▷

$$N_B = \frac{1}{\sqrt{2}} m b \left[\ddot{\theta} \cos\left(\theta + \frac{\pi}{4}\right) - \dot{\theta}^2 \sin\left(\theta + \frac{\pi}{4}\right) \right] + mg$$
 ▷

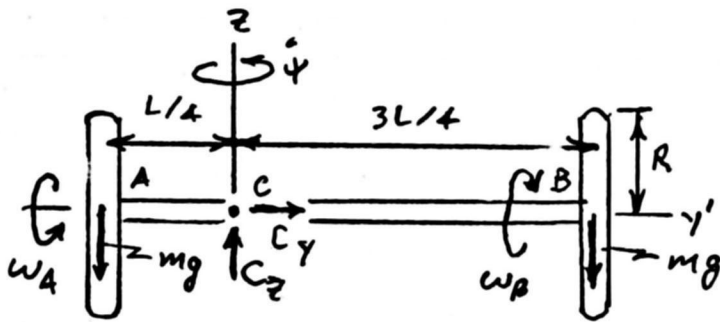
Substitute into moment eq:

$$\frac{2}{\sqrt{2}} m b \left[\ddot{\theta} \cos\left(\theta + \frac{\pi}{4}\right) - \dot{\theta}^2 \sin\left(\theta + \frac{\pi}{4}\right) \right] \frac{b}{\sqrt{2}} \cos\left(\theta + \frac{\pi}{4}\right) + mg \frac{b}{\sqrt{2}} \cos\left(\theta + \frac{\pi}{4}\right) = -\frac{1}{6} m b^2 \ddot{\theta}$$

or $\left[\frac{1}{6} + (\cos\left(\theta + \frac{\pi}{4}\right))^2 \right] \ddot{\theta} - \sin\left(\theta + \frac{\pi}{4}\right) \cos\left(\theta + \frac{\pi}{4}\right) \dot{\theta}^2 = -\frac{g}{\sqrt{2} b} \cos\left(\theta + \frac{\pi}{4}\right)$

$$\left(\frac{2}{3} - \frac{1}{2} \sin 2\theta \right) \ddot{\theta} - \frac{1}{2} (\cos 2\theta) \dot{\theta}^2 = -\frac{1}{2} \frac{g}{b} (\cos \theta - \sin \theta)$$
 ▷

Exercise 6.A1



Given: constant $\omega_A, \omega_B, \dot{\psi}$.

Find: ω_B vs ω_A

Solution: Attach $x'y'z'$ to shaft + instantaneously align xyz for the disks with $x'y'z'$.

$$\Sigma \bar{M}_C = mg \left(-\frac{3L}{4} + \frac{L}{4} \right) \bar{u}$$

The centers of mass are at points A & B, so

$$\Sigma \bar{M}_C = (\dot{H}_A)_A + \bar{r}_{A/C} \times m \bar{a}_A + (\dot{H}_B)_B + \bar{r}_{B/C} \times m \bar{a}_B$$

$$\bar{a}_A = \frac{L}{4} \dot{\psi}^2 \bar{u}', \quad \bar{a}_B = -\frac{3L}{4} \dot{\psi}^2 \bar{u} \Rightarrow \bar{r}_{A/C} \times m \bar{a}_A = \bar{r}_{B/C} \times m \bar{a}_B = \bar{0}$$

$$\text{Thus } (\dot{H}_A)_A + (\dot{H}_B)_B = -\frac{1}{2} mgL \bar{u}$$

$$\bar{\omega}_A = \dot{\psi} \bar{k}' + \omega_A \bar{j} \Rightarrow \bar{\alpha}_A = -\omega_A (\dot{\psi} \bar{k}' \times \bar{j}) = -\omega_A \dot{\psi} \bar{u}$$

$$\bar{\omega}_B = \dot{\psi} \bar{k}' - \omega_B \bar{j} \Rightarrow \bar{\alpha}_B = -\omega_B (\dot{\psi} \bar{k}' \times \bar{j}) = \omega_B \dot{\psi} \bar{u}$$

For each disk $I_{xx} = I_{zz} = \frac{1}{4} mR^2$, $I_{yy} = \frac{1}{2} mR^2$ { centroidal axes

$$\bar{H}_A = mR^2 \left[+\frac{1}{2} \omega_A \bar{j} + \frac{1}{4} \dot{\psi} \bar{k} \right], \quad \bar{H}_B = mR^2 \left[-\frac{1}{2} \omega_B \bar{j} + \frac{1}{4} \dot{\psi} \bar{k} \right]$$

$$\dot{\bar{H}}_A = \frac{\partial \bar{H}_A}{\partial t} + \bar{\omega}_A \times \bar{H}_A = -\frac{1}{2} mR^2 \omega_A \dot{\psi} \bar{u}, \quad \dot{\bar{H}}_B = \frac{1}{2} mR^2 \omega_B \dot{\psi} \bar{u}$$

$$\text{Thus } \frac{1}{2} mR^2 (\omega_B - \omega_A) \dot{\psi} \bar{u} = -\frac{1}{2} mgL \bar{u}$$

$$\omega_A - \omega_B = \frac{gL}{R^2 \dot{\psi}}$$

△