

MCHE 513: Intermediate Dynamics

Fall 2018 – Homework 3

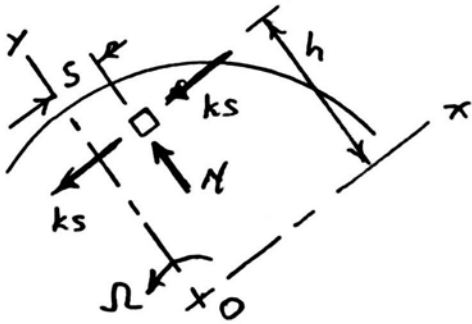
Assigned: Thursday, September 20th
Due: Friday, September 28th, 5pm

Assignment: From “Engineering Dynamics” by Jerry Ginsberg, problems:
3.35, 3.49, 3.56, 4.3, 4.9, 4.16, 4.32

Submission: Emailed *single* pdf document:

- to joshua.vaughan@louisiana.edu
- with subject line and filename ULID-MCHE513-HW3, where ULID is your ULID
- *Note:* Submissions with incorrect filenames or submitted as multiple images/pdfs will be rejected.

Exercise 3.35



Given arbitrary $\Omega(t)$.

Find differential eq for s .

Solution: Attach xyz to the turntable $\Rightarrow \bar{\omega} = \Omega \bar{k}, \bar{\alpha} = \dot{\Omega} \bar{k}$

$$\bar{r}_{p/O} = s\bar{i} + h\bar{j}, (\bar{v}_p)_{xyz} = \dot{s}\bar{i}, (a_p)_{xyz} = \ddot{s}\bar{i}$$

$$\bar{a}_p = \ddot{s}\bar{i} + \dot{\Omega}\bar{k} \times (s\bar{i} + h\bar{j}) - \Omega^2(s\bar{i} + h\bar{j}) + 2\Omega\bar{k} \times \dot{s}\bar{i}$$

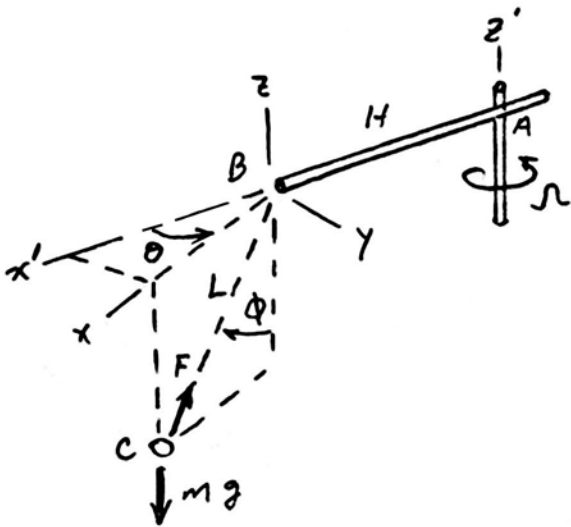
$$\sum \bar{F} \cdot \bar{i} = -2ks = m\bar{a}_p \cdot \bar{i} = m(\ddot{s} - \dot{\Omega}h - \Omega^2s)$$

$$\text{so } \ddot{s} - \dot{\Omega}h - \Omega^2s + \frac{2k}{m}s = 0 \quad \triangle$$

$$\text{If } \Omega \text{ is constant } \Rightarrow \ddot{s} + \left(\frac{2k}{m} - \Omega^2\right)s = 0 \Rightarrow \text{nat freq} = \left(\frac{2k}{m} - \Omega^2\right)^{1/2}$$

If $\Omega > \left(\frac{2k}{m}\right)^{1/2}$, then $s(t)$ has two exponential solutions, one of which grows.

Exercise 3.49



Given constant Ω ,

Find eqs of motion for ϕ & θ .

Solution; Form $\Sigma \vec{F} = m\vec{a}$, then eliminate unknown F .

Attach $x'y'z'$ to the crane, and let xyz rotate by θ relative to $x'y'z'$.

$$\vec{\omega}' = \Omega \bar{k}, \quad \vec{\omega} = \vec{\omega}' + \dot{\theta} \bar{k} = (\Omega + \dot{\theta}) \bar{k}, \quad \vec{\alpha} = \ddot{\theta} \bar{k}$$

$$\vec{a}_B = -H\Omega^2 \bar{z}' = -H\Omega^2 (\cos\theta \bar{z} - \sin\theta \bar{y})$$

Circular motion in xz plane relative to xyz :

$$\vec{r}_{C/B} = L(\sin\phi \bar{i} - \cos\phi \bar{k}), \quad (\vec{v}_C)_{xyz} = \frac{\partial \vec{r}_{C/B}}{\partial t} = L\dot{\phi}(\cos\phi \bar{i} + \sin\phi \bar{k})$$

$$(\vec{a}_C)_{xyz} = \frac{\partial}{\partial t} (\vec{v}_C)_{xyz} = L\ddot{\phi}(\cos\phi \bar{i} + \sin\phi \bar{k}) + L\dot{\phi}^2(-\sin\phi \bar{i} + \cos\phi \bar{k})$$

$$\vec{a}_C = -H\Omega^2(\cos\theta \bar{z} - \sin\theta \bar{y}) + [L\ddot{\phi}\cos\phi - L\dot{\phi}^2\sin\phi] \bar{i}$$

$$+ [L\ddot{\phi}\sin\phi + L\dot{\phi}^2\cos\phi] \bar{k} + \ddot{\theta} \bar{k} \times (L\sin\phi \bar{i} - L\cos\phi \bar{k})$$

$$+ (\Omega + \dot{\theta}) \bar{k} \times [(\Omega + \dot{\theta}) \bar{k} \times (L\sin\phi \bar{i} - L\cos\phi \bar{k})] + 2(\Omega + \dot{\theta}) \bar{k}$$

$$\times L\dot{\phi}(\cos\phi \bar{i} + \sin\phi \bar{k})$$

$$= [L\ddot{\phi}\cos\phi - H\Omega^2\cos\theta - L(\Omega^2 + \dot{\phi}^2 + \dot{\theta}^2)\sin\phi - 2L\Omega\dot{\theta}\sin\phi] \bar{i}$$

$$+ [L\ddot{\theta}\sin\phi + H\Omega^2\sin\theta + 2L(\dot{\phi} + \Omega)\cos\phi] \bar{j} + L(\ddot{\phi}\sin\phi + \dot{\phi}^2\cos\phi) \bar{k}$$

Then $\Sigma \vec{F} = F \bar{e}_{B/C} - mg \bar{k} = m \vec{a}_C$ where $\bar{e}_{B/C} = -\sin\phi \bar{i} + \cos\phi \bar{k}$

Eliminate F by taking components perpendicular to $\bar{e}_{B/C}$ in

\bar{j} and \bar{e}_ϕ directions, where $\bar{e}_\phi = \cos\phi \bar{i} + \sin\phi \bar{k}$

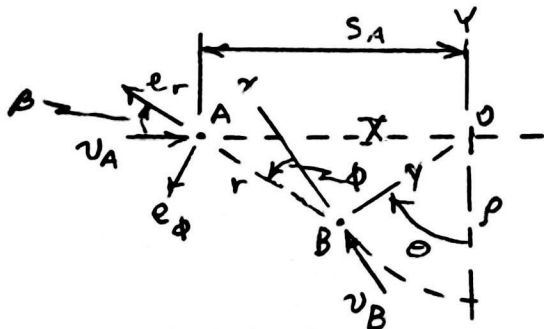
$$\Sigma \vec{F} \cdot \bar{j} = 0 = m \vec{a}_C \cdot \bar{j} \quad \& \quad \Sigma \vec{F} \cdot \bar{e}_\phi = -mg \sin\phi = m \vec{a}_C \cdot \bar{e}_\phi$$

Exercise 3.49 (cont.)

$$\text{Carry out dot products; } L\ddot{\theta}\sin\phi + H\Omega^2\sin\theta + 2L(\dot{\phi} + \Omega)\cos\phi = 0 \quad \Delta$$

$$\text{and } L\ddot{\phi} - H\Omega^2\cos\theta\cos\phi - L(\ddot{\theta} + \Omega)^2\sin\phi\cos\phi + g\sin\phi = 0 \quad \Delta$$

Exercise 3.56



Given constant $v_A = \frac{560}{3.6}$ m/s & $v_B = \frac{1440}{3.6}$ m/s, $\rho = 3200$ m, $\theta = 0$ & $s_A = 5200$ m @ $t=0$.

Find $r, \dot{r}, \phi, \dot{\phi}$ as functions of t .

Solution: Attach xyz to airplane B. Use XYZ as the global coordinates, r & ϕ form polar coordinates relative to xyz , so find $(\vec{v}_A)_{xyz}$ then convert to polar coordinates.

$$\vec{\omega} = \dot{\theta} \vec{k} = \frac{v_B}{\rho} \vec{k} \Rightarrow \theta = \frac{v_B t}{\rho} \quad \text{Also } \dot{s}_A = -v_A \Rightarrow s_A = (s_A)_0 - v_A t$$

$$\vec{v}_B = v_B (\cos \theta \vec{i} + \sin \theta \vec{j}), \quad \vec{v}_A = -v_A \vec{i}$$

$$\vec{r}_{A/B} = (s_A - \rho \sin \theta) \vec{i} + \rho \cos \theta \vec{j}$$

$$\begin{aligned} (\vec{v}_A)_{xyz} &= \vec{v}_A - \vec{v}_B - \vec{\omega} \times \vec{r}_{A/B} \\ &= [-v_A - v_B \cos \theta - (\frac{v_B}{\rho})(-\rho \cos \theta)] \vec{i} + [-v_B \sin \theta - (\frac{v_B}{\rho})(s_A - \rho \sin \theta)] \vec{j} \\ &= -v_A \vec{i} - v_B \frac{s_A}{\rho} \vec{j} \end{aligned}$$

Convert to polar coordinates: $\vec{e}_r = \cos \beta \vec{i} + \sin \beta \vec{j}, \vec{e}_\phi = \sin \beta \vec{i} - \cos \beta \vec{j}$

$$\text{Evaluate } r = |\vec{r}_{A/B}| = [(s_A - \rho \sin \theta)^2 + (\rho \cos \theta)^2]^{1/2}$$

$$= [s_A^2 + \rho^2 - 2\rho s_A \sin \theta]^{1/2}$$

Law of sines for $\triangle OAB$: $\sin \beta = \frac{\rho}{r} \sin(\frac{\pi}{2} - \theta) = \frac{\rho}{r} \cos \theta$

$$\text{Then } \phi = \theta - \beta = \theta - \sin^{-1}(\frac{\rho}{r} \cos \theta)$$

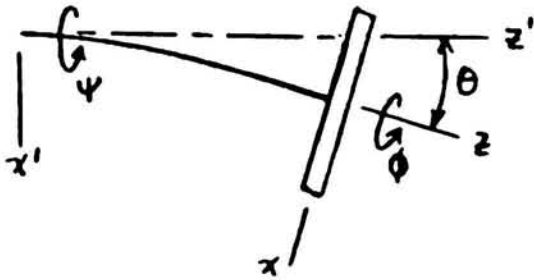
Next set $(\vec{v}_A)_{xyz} = \dot{r} \vec{e}_r + r \dot{\phi} \vec{e}_\phi$, so

$$\dot{r} = (\vec{v}_A)_{xyz} \cdot \vec{e}_r = -v_A \cos \beta - v_B \frac{s_A}{\rho} \sin \beta$$

$$\dot{\phi} = \frac{1}{r} (\vec{v}_A)_{xyz} \cdot \vec{e}_\phi = \frac{1}{r} (-v_A \sin \beta + v_B \frac{s_A}{\rho} \cos \beta)$$

Substitute $v_A, v_B, s_A = 5200 - v_A t, \theta = \frac{v_B t}{\rho}$, then compute other variables.

Exercise 4.3



Given $x'y'z'$ precesses only,
 $\bar{\omega} = 17\bar{i}' - 20\bar{j}' + 48\bar{k}'$ rad/s
 when $\theta = 10^\circ$ & $\phi = -5^\circ$.
 Find $\dot{\psi}$, $\dot{\theta}$, & $\dot{\phi}$, then xyz
 components of $\bar{\omega}$.

Solution: $\bar{\omega} = \dot{\psi}\bar{k}' + \dot{\theta}\bar{j}' + \dot{\phi}\bar{k}$.

Need transformation from $x'y'z'$ to xyz for $\theta = 10^\circ$, $\phi = -5^\circ$

Starting from $x'y'z'$, rotate by θ about y' , then by ϕ about new z :

$$[xyz]^T = [R][x'y'z']^T \text{ where } [R] = [R_z(\phi)][R_y(\theta)]$$

$$[R] = \begin{bmatrix} \cos\phi & \sin\phi & 0 \\ -\sin\phi & \cos\phi & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} \cos\theta & 0 & -\sin\theta \\ 0 & 1 & 0 \\ \sin\theta & 0 & \cos\theta \end{bmatrix}$$

$$= \begin{bmatrix} \cos\phi\cos\theta & \sin\phi & -\cos\phi\sin\theta \\ -\sin\phi\cos\theta & \cos\phi & \sin\phi\sin\theta \\ \sin\theta & 0 & \cos\theta \end{bmatrix}$$

$$= \begin{bmatrix} 0.9810 & -0.0872 & -0.1730 \\ 0.0858 & 0.9962 & -0.0151 \\ 0.1736 & 0 & 0.9848 \end{bmatrix}$$

Thus $\bar{k} = 0.1736\bar{i}' + 0.9848\bar{k}'$

$$\text{Set } \bar{\omega} = 0.1736\dot{\phi}\bar{i}' + \dot{\theta}\bar{j}' + (\dot{\psi} + 0.9848\dot{\phi})\bar{k}' = 17\bar{i}' - 20\bar{j}' + 48\bar{k}'$$

$$\text{Match components: } 0.1736\dot{\phi} = 17, \dot{\theta} = -20, \dot{\psi} + 0.9848\dot{\phi} = 48$$

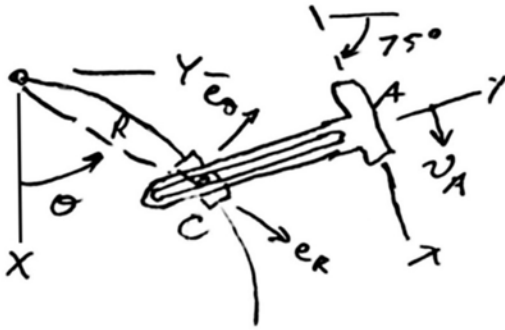
$$\dot{\phi} = 97.90, \dot{\theta} = -20, \dot{\psi} = -48.42 \text{ rad/s}$$

Transform $\bar{\omega}$ components:

$$[\omega_x \ \omega_y \ \omega_z]^T = [R][17 \ -20 \ 48]^T = [10.12 \ -19.19 \ 50.22]^T$$

$$\text{so } \bar{\omega} = 10.12\bar{i} - 19.19\bar{j} + 50.22\bar{k} \text{ rad/s}$$

Exercise 4,9



Given $R = 0.1 \sin(2\theta)$ meter,

$$v_A = 20 \text{ m/s}, \dot{v}_A = 0$$

Find \vec{v} and \vec{a} at $\theta = 1$ rad.

Solution: Attach x, y, z to the slider

$$\begin{aligned} \vec{v}_C &= \dot{R} \vec{e}_R + R \dot{\theta} \vec{e}_\theta \\ &= \vec{v}_A + (\vec{v}_C)_{xyz} \quad (\vec{\omega} = \vec{0}) \end{aligned}$$

Convert to XYZ components: $\vec{e}_R = \cos\theta \vec{i} + \sin\theta \vec{j}$

$$\vec{e}_\theta = -\sin\theta \vec{i} + \cos\theta \vec{j}, \quad \vec{v}_A = v_A (\sin 75^\circ \vec{i} + \cos 75^\circ \vec{j})$$

$$(\vec{v}_C)_{xyz} = u \vec{j} = u (-\cos 75^\circ \vec{i} + \sin 75^\circ \vec{j})$$

$$\text{Also } \dot{R} = \frac{d}{dt}(0.1 \sin(2\theta)) = 0.2 \dot{\theta} \cos(2\theta)$$

$$\begin{aligned} \text{so } \vec{v}_C &= 0.2 \dot{\theta} \cos(2\theta) (\cos\theta \vec{i} + \sin\theta \vec{j}) + (0.1 \sin 2\theta) \dot{\theta} (-\sin\theta \vec{i} + \cos\theta \vec{j}) \\ &= 20 (\sin 75^\circ \vec{j} + \cos 75^\circ \vec{j}) + u (-\cos 75^\circ \vec{i} + \sin 75^\circ \vec{j}) \end{aligned}$$

Match components:

$$\left. \begin{aligned} \vec{v}_C \cdot \vec{i} &= -0.12148 \dot{\theta} = -0.2588 u + 19.318 \\ \vec{v}_C \cdot \vec{j} &= -0.02091 \dot{\theta} = 0.9659 u + 5.176 \end{aligned} \right\} \begin{aligned} \dot{\theta} &= -162.93 \text{ rad/s} \\ u &= -1.833 \text{ m/s} \end{aligned}$$

Need \dot{R} to form \vec{a}_C : $\dot{R} = 0.2 \dot{\theta} \cos(2\theta) = 13.560 \text{ m/s}$

$$\text{Then } \ddot{R} = \frac{d}{dt}(\dot{R}) = 0.2 \ddot{\theta} \cos(2\theta) - 0.4 \dot{\theta}^2 \sin(2\theta) = -0.09323 \ddot{\theta} - 9655$$

$$\text{so } \vec{a}_C = (\ddot{R} - R \dot{\theta}^2) \vec{e}_R + (R \ddot{\theta} + 2 \dot{R} \dot{\theta}) \vec{e}_\theta = \vec{a}_A + (\vec{a}_C)_{xyz} = \vec{0} + \dot{u} \vec{j}$$

$$\vec{a}_C \cdot \vec{i} = (\ddot{R} - R \dot{\theta}^2) \cos\theta + (R \ddot{\theta} + 2 \dot{R} \dot{\theta}) (-\sin\theta) = \dot{u} (-\cos 75^\circ)$$

$$-0.12148 \ddot{\theta} - 2803 = -0.2599 \dot{u}$$

$$\vec{a}_C \cdot \vec{j} = (\ddot{R} - R \dot{\theta}^2) \sin\theta + (R \ddot{\theta} + 2 \dot{R} \dot{\theta}) \cos\theta = \dot{u} \sin 75^\circ$$

$$-0.02091 \ddot{\theta} - 12543 = 0.9659 \dot{u}$$

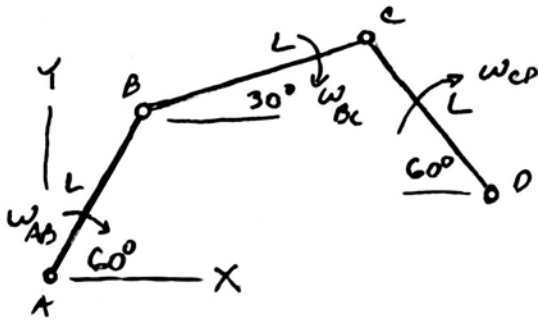
Exercise 4,9 (cont.)

$$\text{Solve: } \ddot{\theta} = -48,50(10^3) \text{ rad/s}^2, \quad \dot{u} = -11,94(10^3) \text{ m/s}^2$$

$$\text{Thus } \vec{v}_c = (\vec{v}_c \cdot \vec{i})\vec{i} + (\vec{v}_c \cdot \vec{j})\vec{j} = 19,793\vec{i} + 3,406\vec{j} \text{ m/s} \quad \blacktriangle$$

$$\vec{a}_c = (\vec{a}_c \cdot \vec{i})\vec{i} + (\vec{a}_c \cdot \vec{j})\vec{j} = (3,089\vec{i} - 11,529\vec{j}) \text{ m/s}^2 \quad \blacktriangle$$

Exercise 4.16



Given constant ω_{AB}

Find $\bar{\omega}$ and $\bar{\alpha}$ for all bars in the given position.

Solution;

$$\bar{v}_B = -\omega_{AB} \bar{k} \times (0.5L\bar{i} + 0.866L\bar{j})$$

$$\begin{aligned} \bar{v}_C &= \bar{v}_B + (-\omega_{BC} \bar{k}) \times (0.866L\bar{i} + 0.5L\bar{j}) \\ &= (-\omega_{CD} \bar{k}) \times (-0.5L\bar{i} + 0.866L\bar{j}) \end{aligned}$$

$$\left. \begin{aligned} \bar{v}_C \cdot \bar{i} &= 0.866\omega_{AB}L + 0.5\omega_{BC}L = 0.866\omega_{CD}L \\ \bar{v}_C \cdot \bar{j} &= -0.5\omega_{AB}L - 0.866\omega_{BC}L = 0.5\omega_{CD}L \end{aligned} \right\}$$

$$\omega_{BC} = -0.866\omega_{AB} \quad \omega_{CD} = 0.5\omega_{AB} \quad \triangleleft$$

$$\text{Then } \bar{a}_B = -\omega_{AB}^2 \bar{r}_{B/A} = -\omega_{AB}^2 (0.5L\bar{i} + 0.866L\bar{j})$$

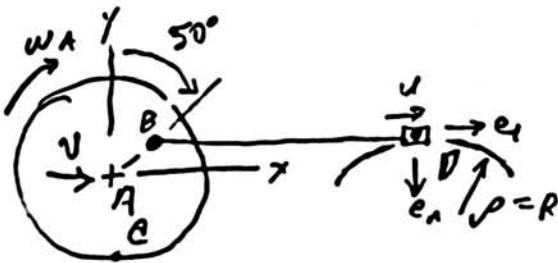
$$\begin{aligned} \bar{a}_C &= \bar{a}_B + (-\dot{\omega}_{BC} \bar{k}) \times (0.866L\bar{i} + 0.5L\bar{j}) - \omega_{BC}^2 (0.866L\bar{i} + 0.5L\bar{j}) \\ &= (-\dot{\omega}_{CD} \bar{k}) \times (-0.5L\bar{i} + 0.866L\bar{j}) - \omega_{CD}^2 (-0.5L\bar{i} + 0.866L\bar{j}) \end{aligned}$$

$$\bar{a}_C \cdot \bar{i} = -0.5\omega_{AB}^2 L + 0.5\dot{\omega}_{BC} L - 0.866\omega_{BC}^2 L = 0.866\dot{\omega}_{CD} L + 0.5\omega_{CD}^2 L$$

$$\bar{a}_C \cdot \bar{j} = -0.866\omega_{AB}^2 L - 0.866\dot{\omega}_{BC} L - 0.5\omega_{BC}^2 L = 0.5\dot{\omega}_{CD} L - 0.866\omega_{CD}^2 L$$

$$\dot{\omega}_{BC} = -0.250\omega_{AB}^2 L, \quad \dot{\omega}_{CD} = -1.616\omega_{AB}^2 L \quad \triangleleft$$

Exercise 4.32



Given constant $v_D = u$, no slippage at contact C

Find \vec{v}_A and \vec{a}_A at this position

Solution: $\vec{v}_D = u\vec{i} \quad \& \quad \vec{a}_D = \frac{u^2}{R}(-\vec{j})$

No slippage $\Rightarrow \omega_A = \frac{v}{R} \quad \& \quad \dot{\omega}_A = \frac{\dot{v}}{R}$

$$\begin{aligned}\vec{v}_B &= \vec{v}_A + \omega_A \times \vec{r}_{B/A} = v\vec{i} + \left(-\frac{v}{R}\vec{k}\right) \times 0.5R(\sin 50^\circ \vec{i} + \cos 50^\circ \vec{j}) \\ &= \vec{v}_D + \omega_{BD} \times \vec{r}_{B/D} = u\vec{i} + \omega_{BD} \vec{k} \times 3R(-\vec{i})\end{aligned}$$

$$\vec{v}_B \cdot \vec{i} = 1.3214v = u$$

$$\vec{v}_B \cdot \vec{j} = -0.3830v = -3R\omega_{BD}$$

$$\left. \begin{array}{l} v = 0.7568u \\ \omega_{BD} = 0.0966 \frac{u}{R} \end{array} \right\} \Delta$$

$$\omega_{BD} = 0.0966 \frac{u}{R}$$

$$\begin{aligned}\text{Then } \vec{a}_B &= \vec{a}_A + \left(-\frac{\dot{v}}{R}\vec{k}\right) \times 0.5R(\sin 50^\circ \vec{i} + \cos 50^\circ \vec{j}) \\ &\quad - \frac{v^2}{R^2} (0.5R)(\sin 50^\circ \vec{i} + \cos 50^\circ \vec{j}) \\ &= \vec{a}_D + \dot{\omega}_{BD} \vec{k} \times (-3R\vec{i}) - \omega_{BD}^2 (-3R\vec{i})\end{aligned}$$

$$\vec{a}_B \cdot \vec{i} = 1.3214\dot{v} - 0.2194 \frac{u^2}{R} = 0.0280 \frac{u^2}{R}$$

$$\vec{a}_B \cdot \vec{j} = -0.3830\dot{v} - 0.18407 \frac{u^2}{R} = -3R\dot{\omega}_{BD} - \frac{u^2}{R}$$

$$\left. \begin{array}{l} \dot{v} = 0.1872 \frac{u^2}{R} \\ \dot{\omega}_{BD} = \dots \end{array} \right\} \Delta$$