



MicroPython

Introduction (cont.)

MCHE 201 – Spring 2019

Dr. Joshua Vaughan

Rougeou 225

`joshua.vaughan@louisiana.edu`

`@Doc_Vaughan`

Comments Review



```
""" This is a block comment. It will  
continue across multiple lines, until it  
is closed with the proper characters """
```

```
# This is a single-line comment
```

```
x = 4 # single-line comments can come  
after code too
```

Print Statement Review



```
# Print a string  
print("Hello.")
```

```
# Print an integer
```

```
x = 10
```

```
print(x) # Prints with no formatting
```

```
print("x = {:d}.".format(x))
```

```
# Print an integer and always include +/- sign
```

```
print("Integer = {:+d}.".format(42))
```

```
# Print a float
```

```
print("Pi is {:f}.".format(3.141592))
```

```
# Print a float with 4 decimal places
```

```
print("Pi is {:.4f}.".format(3.141592))
```

If... then Review



```
# ----- if... else if... else syntax -----
```

```
if (condition1 == True):
```

```
    # Everything indented here is run if condition1 is true
```

```
# if condition1 isn't true, check condition2
```

```
elif (condition2 == True):
```

```
    # Everything indented here is run if condition1 is  
    false, but condition2 is true
```

```
else: # if neither condition1 or condition2 are true, do  
this
```

```
    # Everything indented here is run if both condition1 and  
    condition2 are false
```

For Loops Review



----- for loop syntax -----

```
for counter in sequence:
```

```
# do something
```

```
# Everything indented here is run during each
```

```
# loop until the sequence is finished
```

Variable that's
incremented

What to loop over... a few options for what

----- for loop example -----

```
for counter in range(10):
```

```
# do something
```

```
# This would run 10 times
```

```
# The values of counter would be 0, 1, 2, ..., 9
```

While Loop Review



// ----- while loop syntax -----

while (condition == True):



The condition is tested at the beginning of each iteration

If the condition is true, run the code here.

Once the code in the indented block is finished, check the condition and repeat.

If the condition is not true at the first check above, this will never be run.

Python Functions



Says "This is a function" Function Name Input Variable Names

```
def printRepeatPhrase(repeat, phrase):  
    for counter in range(repeat):  
        print(phrase)
```

Nothing is returned from this function

Must Space/tab Consistently – Remember that in Python, whitespace matters

To Use That Function



```
def printRepeatPhrase(repeat, phrase):  
    for counter in range(repeat):  
        print(phrase)
```

```
# Assign values
```

```
numRepeats = 3
```

```
textToPrint = "Hello"
```

```
# Call the function
```

```
printRepeatPhrase(numRepeats, textToPrint)
```

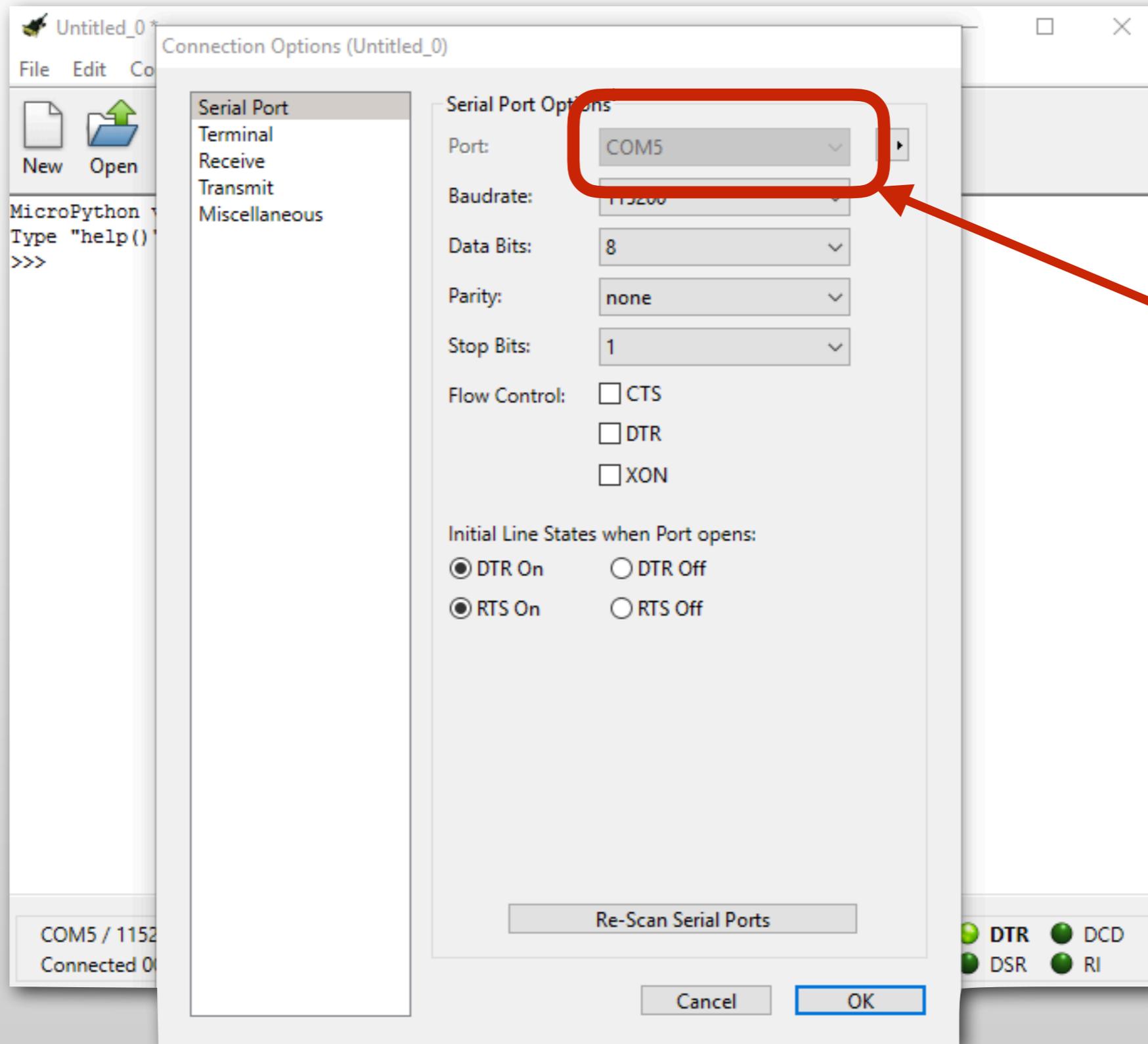
Here, numRepeats is equal to 3, meaning Hello would be printed to the REPL three times.

Connecting to the REPL



- Will need to use some serial terminal
- Serial Settings
 - Baudrate = 115200bps
 - Data bits = 8 bits
 - Parity = None
 - Stop bits = 1
 - Flow control = none

CoolTerm Settings in Windows



This may need to change for your computer

CoolTerm Terminal in Windows...



MicroPython v1.8.7 on 2017-01-08; PYBv1.1 with STM32F405RG
Type "help()" for more information.
>>>

COM5 / 115200 8-N-1
Connected 00:00:20

<input checked="" type="checkbox"/> TX	<input checked="" type="checkbox"/> RTS	<input checked="" type="checkbox"/> DTR	<input checked="" type="checkbox"/> DCD
<input checked="" type="checkbox"/> RX	<input checked="" type="checkbox"/> CTS	<input checked="" type="checkbox"/> DSR	<input checked="" type="checkbox"/> RI

Cool-Term Settings on macOS



Serial Port Options

Port: usbmodem4011712

Baudrate: 115200

Data Bits: 8

Parity: none

Stop Bits: 1

Flow Control: CTS DTR XON

Initial Line States when Port opens:

DTR On DTR Off

RTS On RTS Off

Re-Scan Serial Ports

Cancel OK

LPMS-B-RNI-SP
Disconnected

DTR DCD
DSR RI

This may need to change for your computer

CoolTerm Connection on macOS



```
>>> 2+2
4
>>> import pyb
>>> pyb.LED(1).on()
>>> pyb.LED(1).off()
>>> print("hello")
hello
>>> |
```

usbmodem4011712 / 115200 8-N-1
Connected 00:00:40

TX RTS DTR DCD
RX CTS DSR RI

Special Commands in the REPL



- `Control-d` will perform a soft reboot

```
>>> 2+2
4
>>>
PYB: sync filesystems
PYB: soft reboot
MicroPython v1.8.7 on 2017-01-08; PYBv1.1 with STM32F405RG
Type "help()" for more information.
>>>
```

usbmodem1422 / 115200 8-N-1
Connected 00:00:33

<input checked="" type="checkbox"/> TX	<input checked="" type="checkbox"/> RTS	<input checked="" type="checkbox"/> DTR	<input checked="" type="checkbox"/> DCD
<input checked="" type="checkbox"/> RX	<input checked="" type="checkbox"/> CTS	<input checked="" type="checkbox"/> DSR	<input checked="" type="checkbox"/> RI

Special Commands in the REPL



- `Control-d` will perform a soft reboot
- `Control-c` will kill any running script

Special Commands in the REPL



- `Control-d` will perform a soft reboot
- `Control-c` will kill any running script
- `Control-e` will enter paste mode
 - Paste as usual
 - Use `Control-d` to exit paste mode

```
Untitled_0
New Open Save Connect Disconnect Clear Data Options View Hex Help
>>> 2+2
4
>>>
PYB: sync filesystems
PYB: soft reboot
MicroPython v1.8.7 on 2017-01-08; PYBv1.1 with STM32F405RG
Type "help()" for more information.
>>>
paste mode; Ctrl-C to cancel, Ctrl-D to finish
===
```

Recommended Workflow



- Connect the board to your computer and start the REPL in CoolTerm
- Work on scripts (mostly `main.py` in MCH201) in a local folder with Visual Studio Code
- Drag (or otherwise copy) edited versions to PYBFLASH
- `Control-d` in the REPL to perform a soft reboot and run edited `main.py`

MicroPython Files



- `boot.py`
 - Runs every time the pyboard boots
 - Use for setup and configuration
- `main.py`
 - Executed immediately after `boot.py`
 - Use for your “main” code
 - Can reference other files

Name	Date Modified	Size
boot.py	12/31/14	302 bytes
main.py	12/31/14	34 bytes
pybcdc.inf	12/31/14	3 KB
README.txt	12/31/14	528 bytes

`boot.py` and `main.py` are at the "root" of the PYBFLASH drive (*i.e.* They are not in a folder.)

Minimum Viable boot.py



Minimum “Normal” boot.py



```
# boot.py -- run on boot-up  
# can run arbitrary Python, but best to  
# keep it minimal
```

```
import machine  
import pyb
```

These **import** statements make the code in those modules, libraries, or files available.

Using **imports**



Just prepend the variable or function you want to use with the “name” that you imported

```
# Import the pyboard functions
```

```
import pyb
```

```
# To use a function from pyb, put pyb.  
# in front of the function name.
```

```
RED_LED = pyb.LED(1)
```

Using **imports**



Just prepend the variable or function you want to use with the “name” that you imported

```
# Import time module
```

```
import time
```

```
# sleep for 1 second
```

```
time.sleep(1)
```

```
# sleep for 500 milliseconds
```

```
time.sleep_ms(500)
```

```
# sleep for 10 microseconds
```

```
time.sleep_us(10)
```

Change (local-copy) main.py, to be...



```
# main.py -- put your code here!
```

```
# import the pyboard module
```

```
import pyb
```

```
# Turn on the 1st LED
```

```
pyb.LED(1).on()
```

To run...



- Copy `main.py` to the pyboard
- Open CoolTerm to REPL
- Control-d to perform a soft reboot and run edited `main.py`

Change main.py, to be...



```
# main.py -- put your code here!
```

```
import pyb      # import the pyboard module  
import time    # import the time module
```

```
# Assign the 1st LED to variable RED_LED  
RED_LED = pyb.LED(1)
```

```
# Now, we can control it using RED_LED  
RED_LED.on()      # Turn the RED_LED on  
time.sleep(5)     # Sleep 5 seconds  
RED_LED.off()     # Turn the LED off
```

How could we do this 5 times?



```
import pyb # import the pyboard module
import time # import the time module

# Assign the 1st LED to variable RED_LED
RED_LED = pyb.LED(1)

# This for loop will run 5 times
for counter in range(5):
    RED_LED.on() # Turn the RED_LED on
    time.sleep(2) # Sleep 2 seconds while on
    RED_LED.off() # Turn the LED off
    time.sleep(2) # Sleep 2 seconds while off
```

An Alternate Solution



```
import pyb # import the pyboard module
import time # import the time module

# Assign the 1st LED to variable RED_LED
RED_LED = pyb.LED(1)

# This for loop will run 10 times
for counter in range(10):
    RED_LED.toggle() # Toggle the RED_LED on
    time.sleep(2) # Sleep 2 seconds
```

Where can I find help?



- Full – <http://docs.micropython.org/en/latest/pyboard/>
- Quick Ref – <http://docs.micropython.org/en/latest/pyboard/pyboard/quickref.html>
- REPL specific – <http://docs.micropython.org/en/latest/pyboard/reference/repl.html>
- More links coming to class webpage
- If you don't remember the syntax, look it up

help() in the REPL



```
Untitled_0
New Open Save Connect Disconnect Clear Data Options View Hex Help

>>> help()
Welcome to MicroPython!

For online help please visit http://micropython.org/help/.

Quick overview of commands for the board:
pyb.info()      -- print some general information
pyb.delay(n)    -- wait for n milliseconds
pyb.millis()    -- get number of milliseconds since hard reset
pyb.Switch()    -- create a switch object
                  Switch methods: (), callback(f)
pyb.LED(n)      -- create an LED object for LED n (n=1,2,3,4)
                  LED methods: on(), off(), toggle(), intensity(<n>)
pyb.Pin(pin)    -- get a pin, eg pyb.Pin('X1')
pyb.Pin(pin, m, [p]) -- get a pin and configure it for IO mode m, pull mode p
                  Pin methods: init(..), value([v]), high(), low()
pyb.ExtInt(pin, m, p, callback) -- create an external interrupt object
pyb.ADC(pin)    -- make an analog object from a pin
                  ADC methods: read(), read_timed(buf, freq)
pyb.DAC(port)  -- make a DAC object
                  DAC methods: triangle(freq), write(n), write_timed(buf, freq)
pyb.RTC()      -- make an RTC object; methods: datetime([val])
pyb.rng()      -- get a 30-bit hardware random number
pyb.Servo(n)   -- create Servo object for servo n (n=1,2,3,4)

usbmodem1422 / 115200 8-N-1
Connected 00:00:43
● TX ● RTS ● DTR ● DCD
● RX ● CTS ● DSR ● RI
```

Tab-completion in REPL



- Start your command, then hit tab to:
 - See options for completion
 - If only 1 option, fill in the complete function or variable name

Tab-completion in REPL



- Start
- S
- l
- r

Untitled_0

New Open Save Connect Disconnect Clear Data Options View Hex Help

```
>>> import pyb
>>> pyb.
__name__      bootloader      hard_reset      info
unique_id     freq            repl_info       wfi
disable_irq   enable_irq      stop             standby
main          repl_uart      usb_mode        hid_mouse
hid_keyboard  USB_VCP        USB_HID         have_cdc
hid           millis          elapsed_millis  micros
elapsed_micros delay           udelay          sync
mount         Timer          rng             RTC
Pin           ExtInt         pwm             servo
Servo         Switch         Flash           SD
SDCard        LED            I2C             SPI
UART          CAN            ADC             ADCA11
DAC           Accel          LCD
```

>>> pyb.|

usbmodem1422 / 115200 8-N-1
Connected 00:02:32

TX RTS DTR DCD
RX CTS DSR RI

ble

Tab-completion in REPL



- Start
- S
- l
- n

Untitled_0

New Open Save Connect Disconnect Clear Data Options View Hex Help

```
>>> pyb.LED.  
on          off          toggle          intensity  
>>> pyb.LED.
```

usbmodem1422 / 115200 8-N-1
Connected 00:04:58

<input checked="" type="checkbox"/> TX	<input checked="" type="checkbox"/> RTS	<input checked="" type="checkbox"/> DTR	<input checked="" type="checkbox"/> DCD
<input checked="" type="checkbox"/> RX	<input checked="" type="checkbox"/> CTS	<input checked="" type="checkbox"/> DSR	<input checked="" type="checkbox"/> RI

ble

Tab-completion in REPL



- Start
- S
- l
- r

Untitled_0

New Open Save Connect Disconnect Clear Data Options View Hex Help

```
>>> import time
>>> time.
__name__      localtime      mktime      time
sleep         sleep_ms      sleep_us     ticks_ms
ticks_us      ticks_cpu     ticks_add    ticks_diff
>>> time.
```

usbmodem1422 / 115200 8-N-1
Connected 00:05:38

TX RTS DTR DCD
RX CTS DSR RI

ble

In-class Exercise 1



- Print the odd numbers between 1 and 27
- *Hint:* A for loop would be a good way to do this.

In-class Exercise 2



- Print the odd numbers between 1 and 27
- When the number is 13, print “Counter = 13... Bad Luck!!!” and turn on the red LED
- *Hint:* Modify/extend the method you used to solve Exercise 1.