



# **MicroPython**

# **Introduction**

## **MCHE 201 – Spring 2019**

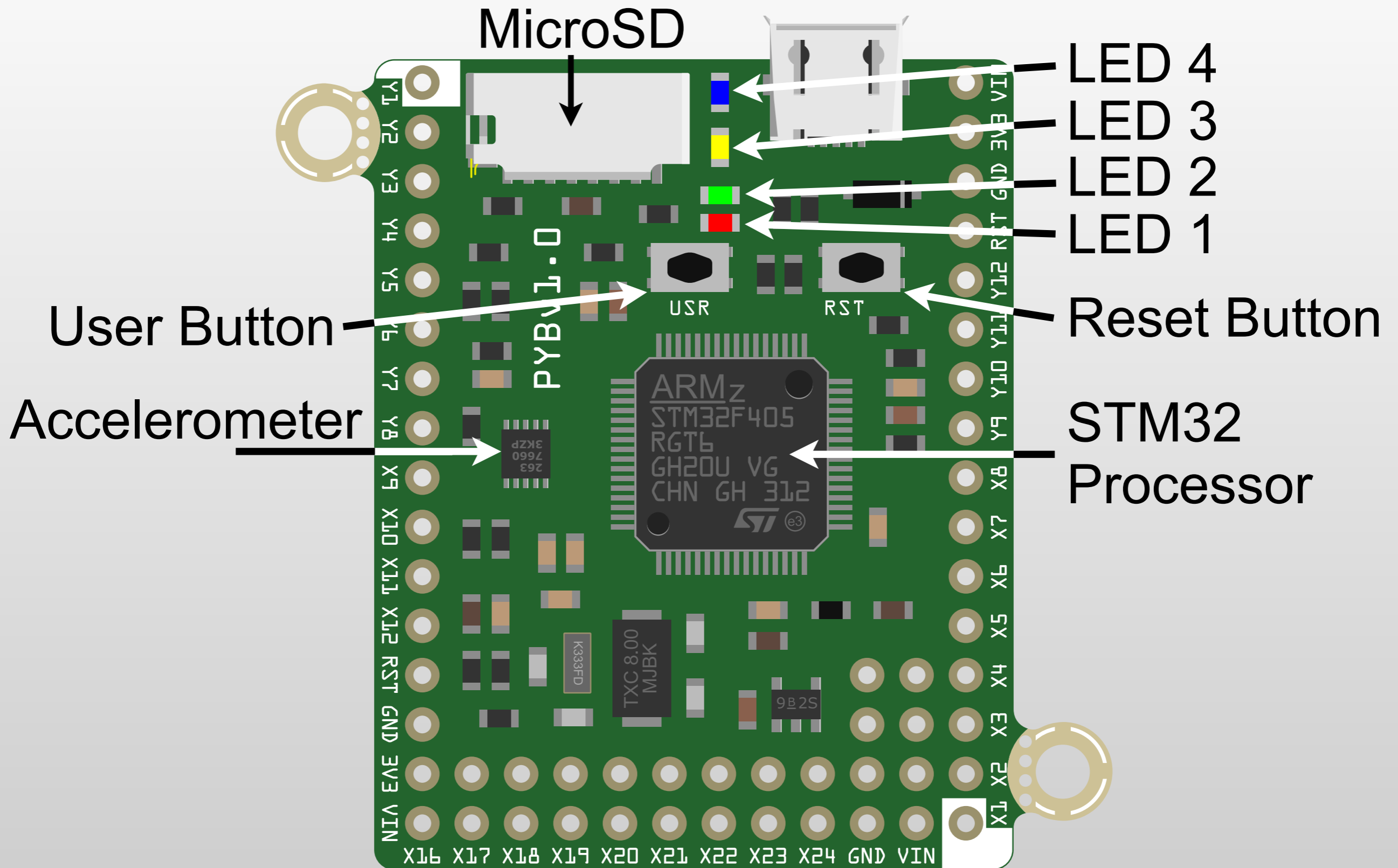
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# The pyboard



# Why Python?

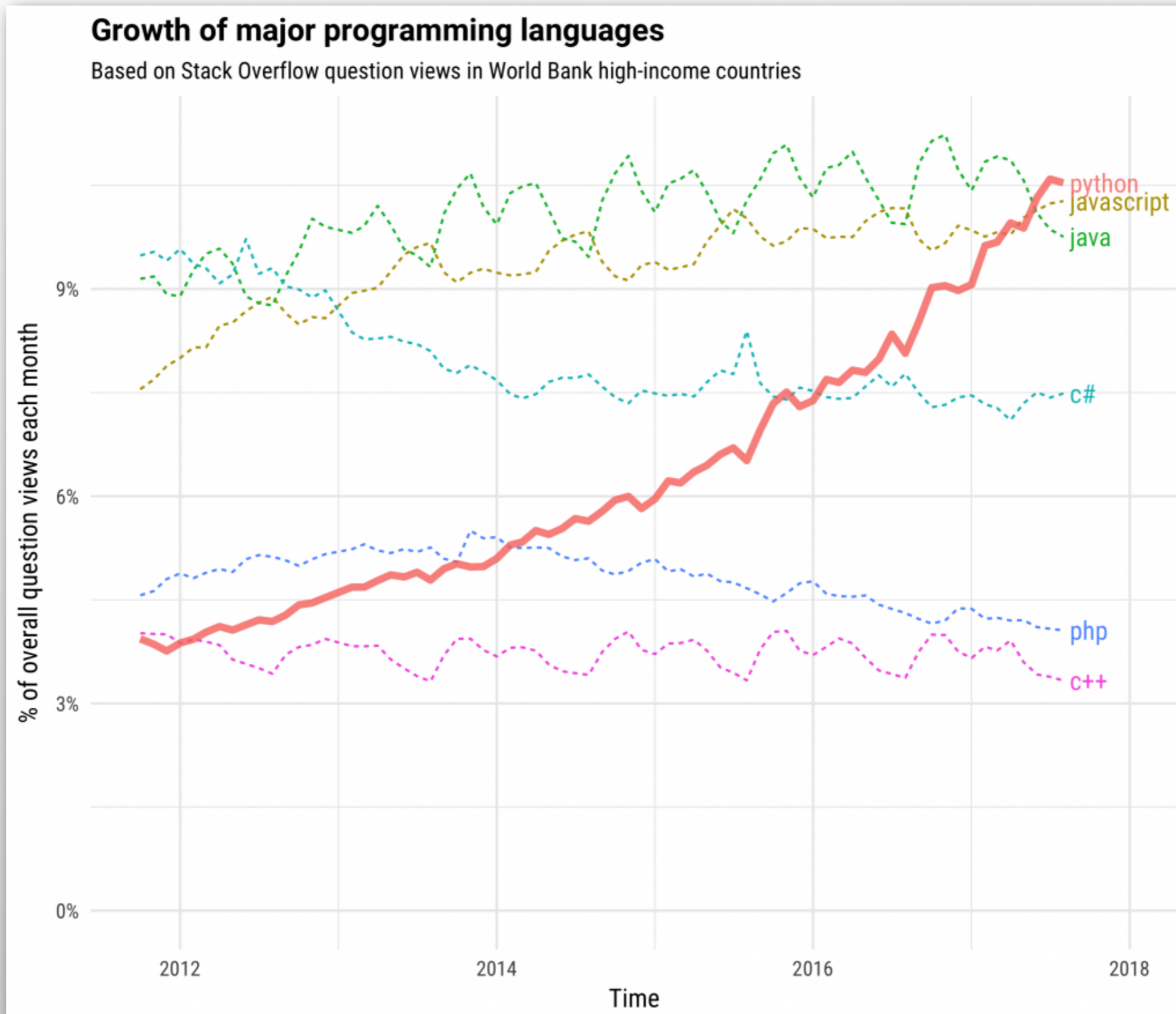


Figure via: <https://stackoverflow.blog/2017/09/06/incredible-growth-python/>

# Why not Arduino?



- Python is a general-purpose language
  - Instagram, Google, *etc.* use it *extensively*
  - Many robotics tools are built around it
  - <http://lorenabarba.com/blog/why-i-push-for-python/>
- The pyboard is *significantly* more powerful than equivalently-priced Arduino boards



# System Setup

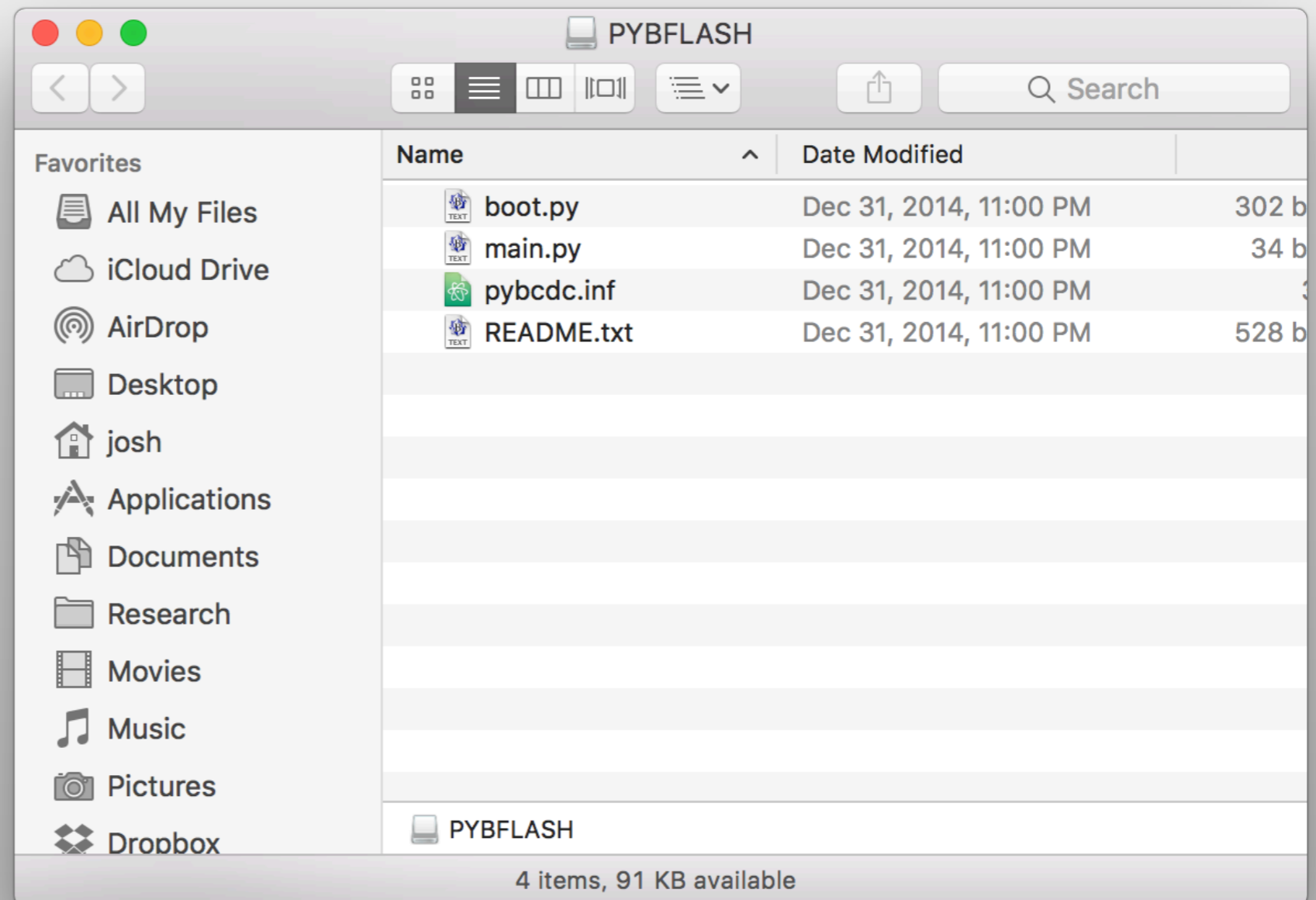


- You'll need a plain-text editor
  - *Many* options that programmers *really* argue about
  - Visual Studio Code – <https://code.visualstudio.com>
- Bookmark the documentation and quick reference
  - Full – <http://docs.micropython.org/en/latest/pyboard/>
  - Quick Ref – <http://docs.micropython.org/en/latest/pyboard/pyboard/quickref.html>
  - If you don't remember the syntax, *look it up*

# Connecting to the pyboard



- Just plug in Micro-USB cable
- The board will show up as a USB disk with files:
  - `boot.py`
  - `main.py`
  - `README.txt`
  - `pybcdc.inf`



**STOP – Before anything else**



**Save those default files to  
a safe place on your  
computer!**

# WARNING!!!



- Do ***NOT*** edit the files directly on the PYBFLASH drive
- Instead:
  - Work on a version on your computer
  - Then, copy that file to the pyboard
- Be sure to eject/unmount before unplugging

**The pyboard's flash memory can get corrupted much easier than a normal "thumb drive."**

# On Windows...



- You may be asked to set up the device when you plug it in... *cancel* that prompt.
- Try to connect to the board first, you likely will *not* need to install the driver.
- If you do need to install a driver
  - The `pybcdc.inf` file from the disk is the driver
  - <http://micropython.org/resources/Micro-Python-Windows-setup.pdf>

# Getting to the REPL



- We'll talk to the board over serial, often connecting to the Read, Evaluate, Print, Loop (REPL) prompt
- Like the text editor, there are many options
  - On macOS:
    - ◆ CoolTerm – <http://freeware.the-meiers.org>
    - ◆ Using screen from the Terminal app
    - ◆ goSerial – <http://www.furrysoft.de/?page=goserial>
    - ◆ Serial Tools – <http://www.w7ay.net/site/Applications/Serial%20Tools/index.html>
  - On Windows:
    - ◆ CoolTerm – <http://freeware.the-meiers.org>
    - ◆ HyperTerminal is still installed by default on some dist.
    - ◆ Putty – <https://www.chiark.greenend.org.uk/~sgtatham/putty/latest.html>

# Code Sharing – GitHub.com



<https://github.com/DocVaughan/MCHE201---Intro-to-Eng-Design>

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DocVaughan/MCHE201---Intro-to-Eng-Design: C... - GitHub

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Code Issues 0 Pull requests 0 Pulse Graphs

Code supporting MCHE201: Introduction to Engineering Design at the University of Louisiana at Lafayette.

20 commits 4 branches 0 releases 1 contributor

Branch: Spring... New pull request New file Find file HTTPS https://github.com/DocVaughan/ Download ZIP

DocVaughan Merge pull request #2 from DocVaughan/Fall-2015 Latest commit 1cc4052 20 days ago

Arduino	Added basic IR sensor code	3 months ago
LaTeX @ 281ff84	Added LaTeX Report submodule	a year ago
Licenses	Added license file	a year ago
Python - Track Controller	Added socket.io library, updated styling	3 months ago
.gitmodules	Added LaTeX Report submodule	a year ago
README.md	Update README.md	a year ago

README.md

## MCHE201 - Introduction to Engineering Design

Code supporting [MCHE201: Introduction to Engineering Design](#) at the [University of Louisiana at Lafayette](#).

More information can likely be found at: <http://www.ucs.louisiana.edu/~jev9637/MCHE201.html>



# Code Sharing – GitHub.com



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Code supporting MCHE201: Introduction to Engineering Design at the University of Louisiana at Lafayette.

20 commits 4 branches

Branch: Spring... [New pull request](#) [New file](#) [Find file](#)

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Latest commit **fcca652** 25 days ago

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# Comments



- Completely ignored by the Python interpreter
- Comments allow you to explain your code inline for:
  - your co-workers/teammates
  - you, in the future
- To comment a single line, use # before your comment
- To create a block comment, begin with `"""` and end with `"""`

# Comments



```
""" This is a block comment. It will  
continue across multiple lines, until it  
is closed with the proper characters """
```

```
# This is a single-line comment
```

```
x = 4 # Comments can go here too
```

# Block Comments



- Block comments are also a good way to begin any file you write.
- It's good practice to include:
  - The filename
  - The purpose of the code
  - Any external requirements (other files or hardware needed to make this one work)
  - What inputs are needed, if any
  - What the output is, if any
  - The version number, recent modifications, and your contact info

# Block Comments – Boilerplate



```
"""-----
```

```
filename.py
```

```
Some description of functionality
```

```
Optional links to relevant documentation
```

```
Created: mm/dd/yy - Name - email@louisiana.edu
```

```
Modified:
```

```
* mm/dd/yy - Name (email if not same person as above)
```

```
- major change 1
```

```
- major change 2
```

```
* mm/dd/yy - Name (email if not same person as above)
```

```
- major change 1
```

```
-----"""
```

# Block Comments – Boilerplate



```
# -----  
# filename.py  
#  
# Some description of functionality  
#  
# Optional Link to relevant documentation  
#  
# Created: mm/dd/yy - Name - email@louisiana.edu  
#  
# Modified:  
# * mm/dd/yy - Name (email if not same person as above)  
#   - major change 1  
#   - major change 2  
# * mm/dd/yy - Name (email if not same person as above)  
#   - major change 1  
# -----
```

# Block Comments – Example



```
#####  
# main.py  
#  
# This script will control a single DC motor using a Texas Instruments DRV8871  
# motor driver. It should work with all DRV8871 driver breakouts, but has only  
# been tested with the Adafruit one:  
#   https://www.adafruit.com/product/3190  
#  
# Motor driver spec sheet  
#   https://cdn-shop.adafruit.com/product-files/3190/drv8871.pdf  
#  
# Adafruit Overview of the board:  
#   https://learn.adafruit.com/adafruit-drv8871-brushed-dc-motor-driver-breakout  
#  
# Created: 11/06/17  
#   - Joshua Vaughan  
#   - joshua.vaughan@louisiana.edu  
#   - http://www.uclouisiana.edu/~jev9637  
#  
# Modified:  
#   *  
#  
# TODO:  
#   *  
#####
```

# Literate Programming



- Write out what you want your code to do in plain English (or your preferred language)... Be explicit about *every* step
- Translate this into comments in your code file
- Then, write the code to implement the functionality

***Key Point:* If you can't explain what you want the code to do in plain English, writing code to do that will be difficult.**

# Variables in Python



- Unlike Arduino (or other C-based languages), we don't need to specify the variable type
- Python is a *dynamically-typed* language
  - It will figure out what type of variable you need
  - That type can/will change if you reassign the variable to a different type

***TIP:* Give your variables meaningful names. A few extra keystrokes are worth the improved understanding and easier debugging.**



# Variable Declaration Examples



```
# Booleans are True or False.
```

```
binaryConditionCheck = False
```

```
youCantHandleThe = True
```

```
# Integers are, well, integers
```

```
integerVariable = -1
```

```
motorSpeed = 75
```

```
# Floats are decimal numbers
```

```
floatVariable = 1.0
```

```
preciseMotorSpeed = 75.275
```

```
# Strings hold text, put between "-"
```

```
myString = "some text"
```

# Variable Declaration (cont.)



```
# We can assign multiple variables at the  
# same time
```

```
#
```

```
# Note: Be careful with this, only group  
#       variables that make sense to  
#       group logically.
```

```
small, medium, large = 1, 3, 9
```

```
IP_ADDRESS, PORT = "192.168.0.100", 2390
```

# Variable Naming Conventions



- Give your variables meaningful names
    - `armLength = 15` is *much* clearer than `l = 15`
    - `delay_time = 0.25` is *much* clearer than `t = 0.25`
  - Use a consistent variable style
    - *camel case* – `armLength`
    - Underscores for spaces – `delay_time`
    - All caps for constants – `LED_PIN`
- Pick one of these and stick to it**

# Variable Scope



- Scope – essentially what functions are able to read/write to a particular variable
- Variables defined:
  - Outside of all functions have *global* scope
    - ♦ Can be *read* anywhere
    - ♦ Need some special syntax to *write* to them
  - Inside a function are accessible inside *that* function
- Limit scope to as small as possible

# Python Functions



Says "This is a function"      The Function Name

```
def myMultiplyFunction(x, y):  
    result = x * y  
    return result
```

Input Variable Names

Return Definition

Must Space/tab Consistently

**TIP: Give your functions meaningful names. A few extra keystrokes are worth the improved understanding and easier debugging.**

- In Python, whitespace matters
- *Note:* All of these have more formal names.

# To Use That Function



```
def myMultiplyFunction(x, y):  
    result = x * y  
    return result
```

```
# Assign values to a and b
```

```
a = 2
```

```
b = 3
```

```
# Call the function, and store the result in c
```

```
c = myMultiplyFunction(a, b) # c=6
```

```
# This works fine with other types too
```

```
a, b = 1.2, 3.75
```

```
c = myMultiplyFunction(a, b) # c=4.5
```

# Use Functions!!!



- Aim for each function having a single function
- This makes:
  - execution more predictable and easier to debug
  - the code more-easily reusable
    - ◆ Reuse limits likelihood of typos and other bugs
    - ◆ Makes code more readable
    - ◆ Makes program logic easier to follow

***TIP:* Give your functions meaningful names. A few extra keystrokes are worth the improved understanding and easier debugging.**

# Example



```
wait_for_start_button()

pyb.delay_ms(500) # pause 500ms after start button

drive_forward(4) # drive forward 4 seconds

rotate_arm(75) # rotate the arm 75 deg

pyb.delay_ms(1000) # Pause for 1000ms (1s)

rotate_arm(0) # rotate the arm back to 0

drive_backward(2) # drive backward 2 seconds
```



# How do I debug my code?

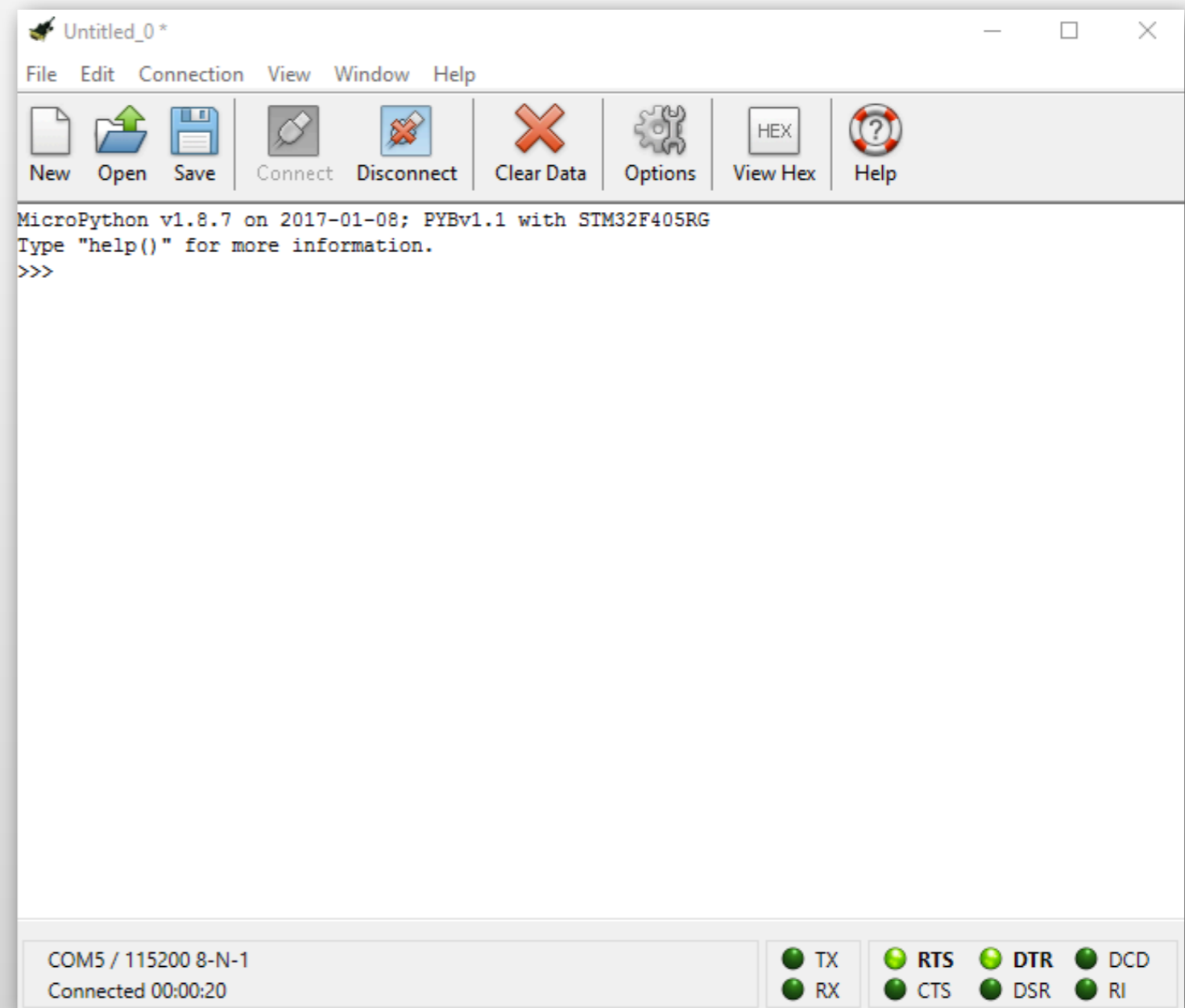


- The computer will only do *exactly* what you tell it. Nothing more. Nothing less.
- Don't assume anything!... the computer is dumb.
  - Work line-by-line “What happens on *this* line?”
  - Output values in runtime via `print` statements

# Using the REPL



- Allows the pyboard to communicate with the computer during runtime
- Can be used for:
  - Prototyping
  - Debugging
  - Execution monitoring



# Clarity in the print Statements



- We can format the numbers/items that we print out.
- A great overview: <https://pyformat.info>
- Syntax is:

```
print( "String {formatting spec}" .format(variable) )
```

# Formatted Output Examples



*# Print an integer*

```
print( "Integer {:d}.".format(42) )
```

*# Print an integer and always include +/- sign*

```
print( "Integer {:+d}.".format(42) )
```

*# Print an integer and always include at least 4  
# "places"*

```
print( "Integer {:4d}.".format(42) )
```

*# Print an integer, always include at least 4  
# "places," and pad with zeros*

```
print( "Integer {:04d}.".format(42) )
```

# Formatted Output (cont.)



*# Print a float*

```
print("Pi is {:.f}.".format(3.141592))
```

*# Print a float with 4 decimal places*

```
print("Pi is {:.4f}.".format(3.141592))
```

*# Print a float and always include at least 9  
# "places" with 2 decimal places*

```
print("Pi is {:9.2f}.".format(3.141592))
```

*# Print a float and always include at least 9  
# "places" and pad with zeros*

```
print("Pi is {:09.2f}.".format(3.141592))
```

# Special Characters to Know



- `\n` = new line
- `\r` = carriage return
- `\t` = tab

```
# Define pi  
pi = 3.141592
```

```
print("Pi is {:.4f}.\n2pi is {:.4f}".format(pi, 2*pi))
```

```
print("Pi is {:.4f}.\t2pi is {:.4f}".format(pi, 2*pi))
```

# Control Structures



- Numerous ways to control program flow
- Ways to conditionally execute
  - If... then
  - For loops
  - While loops

# Comparison Operators



```
# ----- Comparison syntax -----  
# These evaluate to True (1) or False (0)  
  
x == y # True if x is equal to y, False otherwise  
x != y # True if x is not equal to y, False otherwise  
x < y  # True if x is less than y, False otherwise  
x > y  # True if x is greater than y, False otherwise  
x <= y # True if x is less than or equal to y, False  
otherwise  
x >= y # True if x is greater than or equal to y,  
False otherwise
```



# If... then Example



```
# ----- if... elif... else example -----  
# Note: this assumes all variables have been defined,  
# etc.
```

```
if (counter < 10):  
    # Code indented here will run if counter is less than  
    10
```

```
elif (counter >= 20):  
    # Code indented here will run if counter is greater  
    than or equal to 20
```

```
else:  
    # Code indented here will only run if both counter is  
    neither less than 10 or greater than or equal to 20
```

# If... then Example 2



```
a = 2 # Define the value of a
```

```
if (a > 5):  
    print("Tell me something, girl")
```

```
elif (a == 2):  
    print("Are you happy in this modern world")
```

```
else:  
    print("Or do you need more?")
```

Here, a is equal to 2, so the **elif** condition is True. The code indented under it is run, meaning **Are you happy in this modern world** would be printed.

# If... then Example 3



```
a = 2 # Define the value of a
b = 3 # Define the value of b
```

```
if (a + b > 5):
    print("Kiki, do you love me?")
```

```
elif (b - a == 2):
    print("Are you riding?")
```

```
else:
    print("Say you'll never ever leave...")
```

Neither the **if** or the **elif** condition is True. So, the code in **else** is run, meaning **Say you'll never ever leave...** would be printed.

# If... then Example 4



```
sensedStartSignal = True # Start was sensed
```

```
if (sensedStartSignal):
```

```
    print("Sensed start signal. Starting robot.")
```

```
    # Code to run once the start signal was sensed
```

```
else:
```

```
    print("Checking start signal...")
```

```
    # Code to check the start signal
```

The **if** is True. So, the code in **if** is run, meaning **Sensed start signal. Starting robot.** would be printed and other code in that indented block would run.

# Basic For Loops



```
# ----- for loop syntax -----  
for counter in sequence:  
    # do something  
    # Everything indented here is run during each  
    # loop until the sequence is finished
```

# Basic For Loops



# ----- for loop syntax -----

```
for counter in sequence:
```

```
# do something
```

```
# Everything indented here is run during each
```

```
# loop until the sequence is finished
```

Variable that's  
incremented

What to loop over... a few options for what

# ----- for loop example -----

```
for counter in range(10):
```

```
# do something
```

```
# This would run 10 times
```

```
# The values of counter would be 0, 1, 2, ..., 9
```

# For Loop Example



```
list_of_pies = ["apple", "cherry", "pumpkin"]
```

```
for pie in list_of_pies:  
    print("I think {} pies are delicious!".format(pie))
```

Prints out to the REPL:

```
I think apple pies are delicious!
```

```
I think cherry pies are delicious!
```

```
I think pumpkin pies are delicious!
```

# For Loop Example



```
list_of_pies = ["apple", "cherry", "pumpkin"]
```

```
for index, pie in enumerate(list_of_pies):  
    print("The number {:d} pie in the list is  
    {}".format(index, pie))
```

Prints out to the REPL:

```
The number 0 pie in the list is apple.
```

```
The number 1 pie in the list is cherry.
```

```
The number 2 pie in the list is pumpkin.
```



# While Loops



// ----- while loop syntax -----

**while** (condition == True):

← The condition is tested at the beginning of each iteration

# If the condition is True, run the code here.

# Once the code in the indented block is finished, check the condition and repeat.

# If the condition is not True at the first check above, this will never be run.

# While Loop Example



```
# ----- while loop example -----  
index = 0
```

```
while (index < 10):  
    print("Index = {:d}".format(index))  
    index = index + 2
```

## Prints

```
Index = 0  
Index = 2  
Index = 4  
Index = 6  
Index = 8
```

# While Loop Example 2



```
# ----- while loop example -----  
index = 0  
  
while (index < 10):  
    if (index == 3):  
        print("Index = {}".format(index))  
  
    index = index + 1
```

Prints to the Serial Monitor  
Index = 3

# While Loop Example 3



```
# ----- while loop example -----  
keepRunning = True  
index = 0  
  
while(keepRunning):  
    print("Running.")  
  
    if (index >= 10):  
        keepRunning = False  
  
    pyb.delay(100) # sleep 100ms  
  
    index = index + 1  
  
print("Stopped.")
```

Loops 10 times, printing "Running" and delaying 100ms each time. Then, prints "Stopped."

# For next Thursday...



- **BEFORE** next week:
  - Install the driver, if necessary for Windows.
  - Install Visual Studio Code (or other text editor) on your computer.
  - Install CoolTerm on your computer.
  - Look through these notes. These are the foundation for all the programming we'll do.
  - Review the MicroPython Getting Started Guide at <http://docs.micropython.org/en/latest/pyboard/pyboard/tutorial/index.html>
- Bring laptop and kit to class