



# **Controls, Robotics, and Automation With Respect for Human Interaction**

**Dr. Joshua Vaughan**

Rougeou 225

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`http://www.ucslouisiana.edu/~jev9637/`



# ***C.R.A.W.LAB***

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# First, Some Info on Me



- Grew up in Southern Virginia
- Bachelor's from Hampden-Sydney College in May 2002
  - Double Major: Physics and Applied Math
  - 4-year starting pitcher



# Grad. School



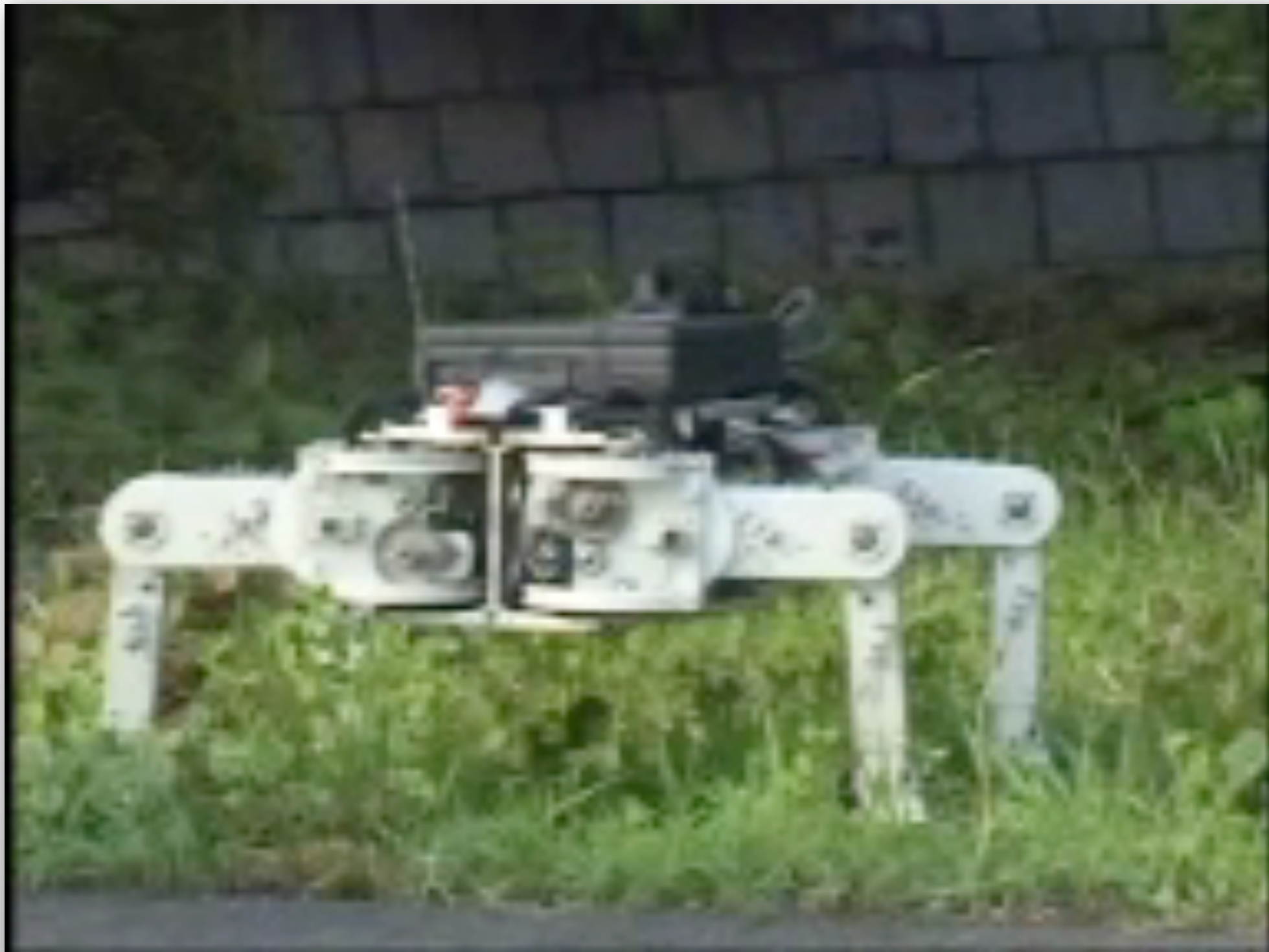
- Graduate School at Georgia Tech
  - Advisor: Dr. William Singhose
  - M.S. in May 2004
    - ♦ Thesis: *Active and Semi-Active Control to Counter Vehicle Payload Variation*
  - Ph.D. in August 2008
    - ♦ Thesis: *Dynamics and Control of Mobile Cranes*



# Postdoc



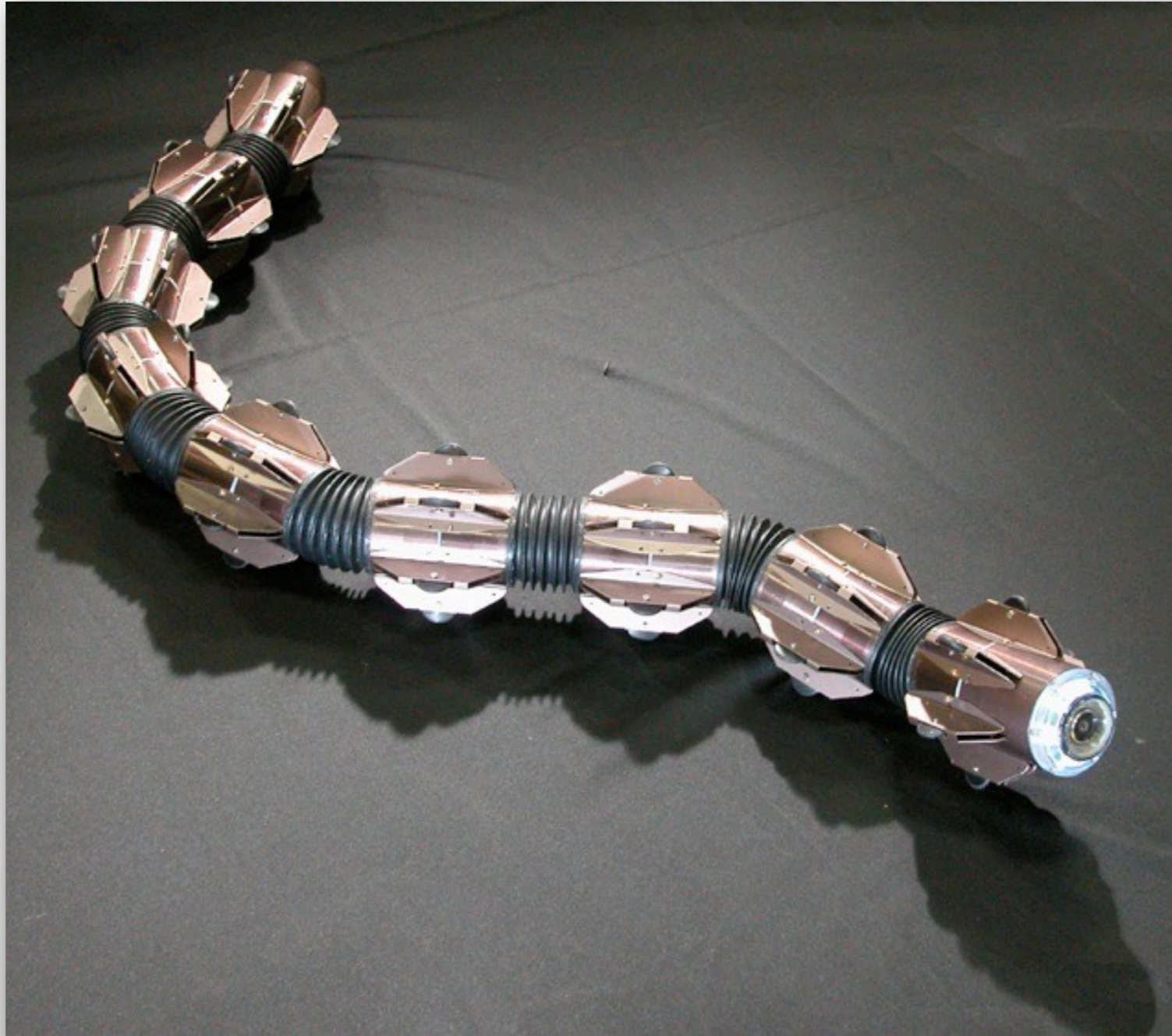
- Tokyo Institute of Technology with Dr. Shigeo Hirose



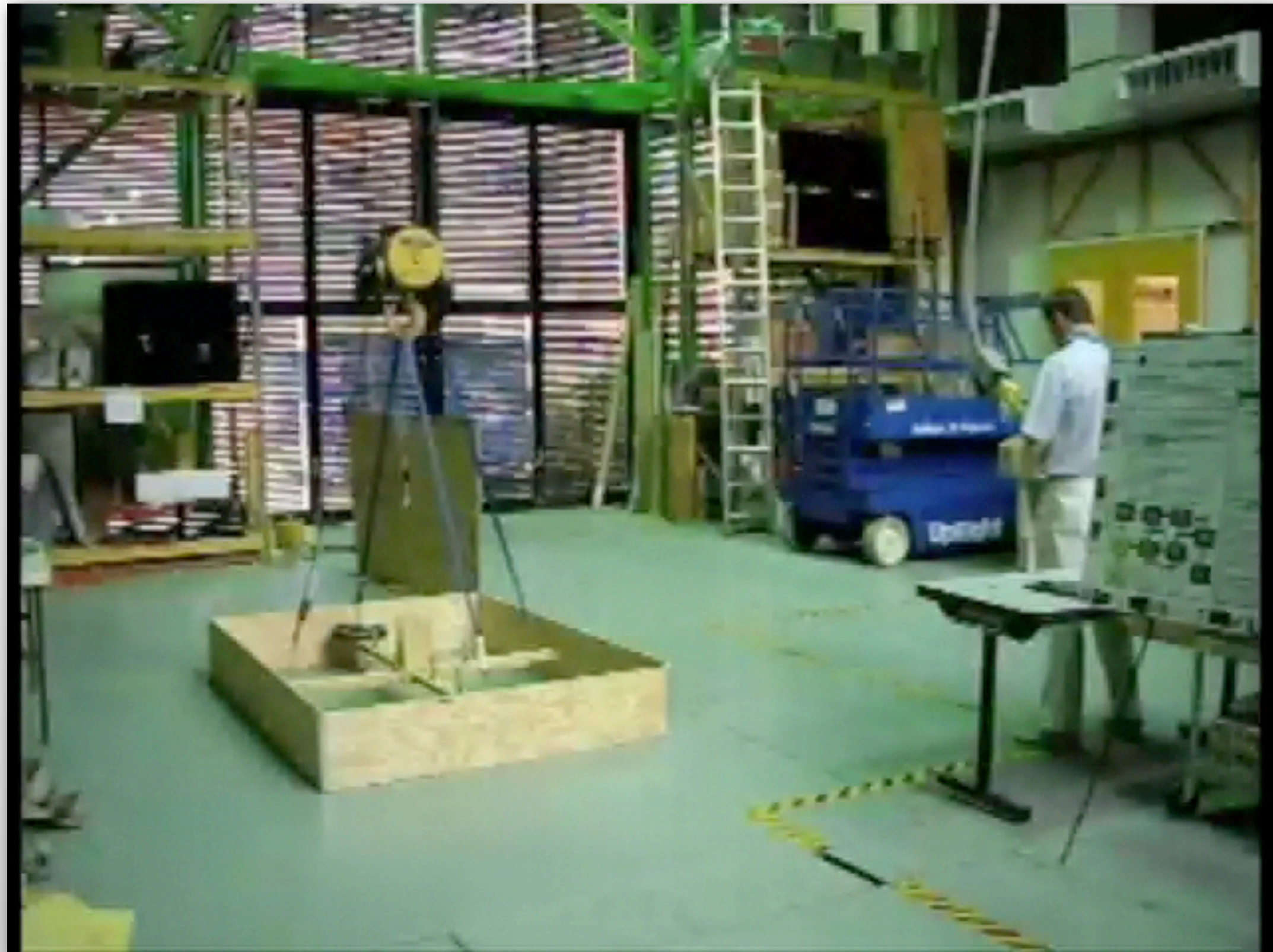
# Postdoc



- Tokyo Institute of Technology with Dr. Shigeo Hirose



# 10-ton Bridge Crane



# High-voltage Power Lines



- How would you inspect these?

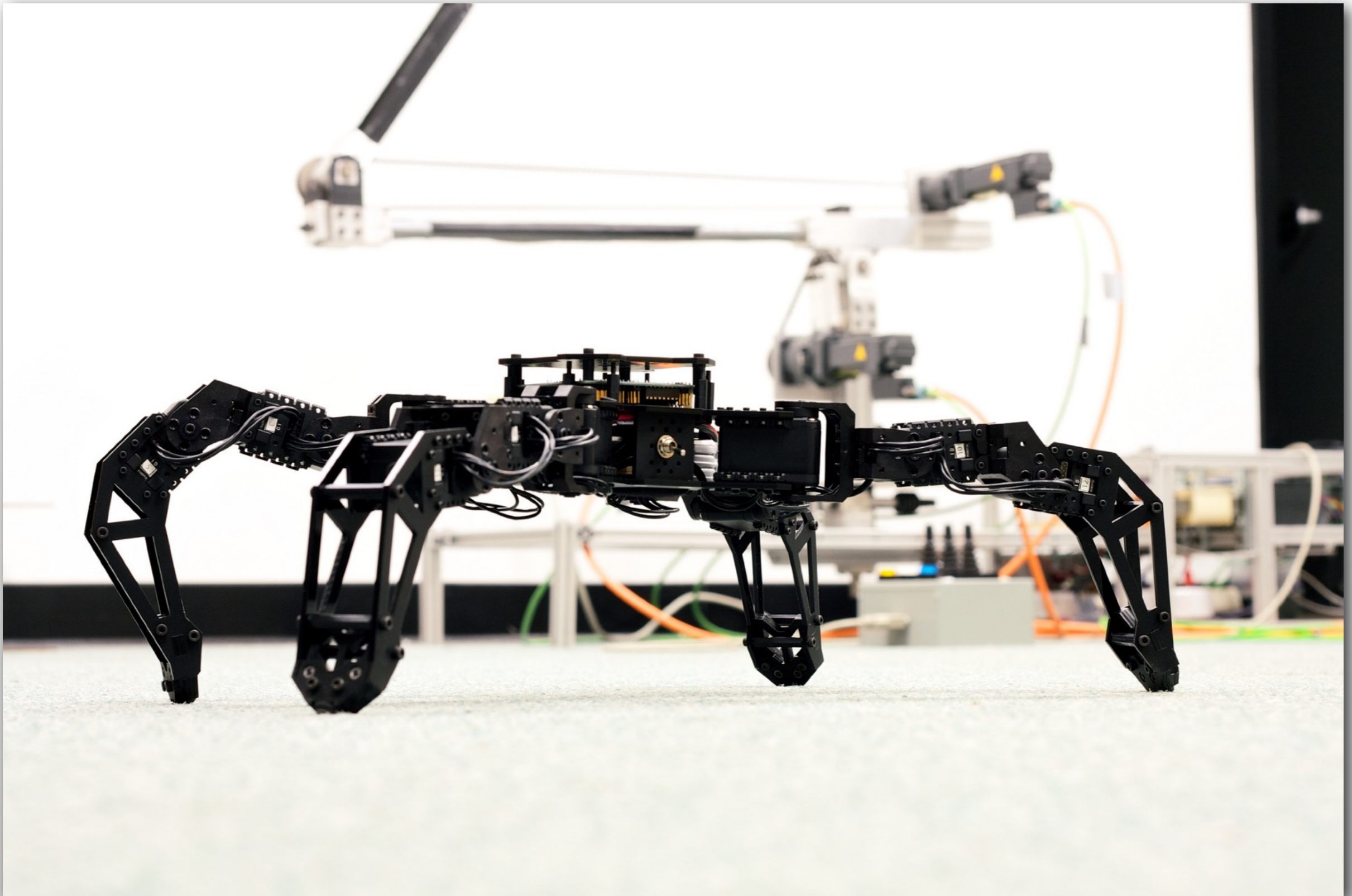




# Current State-of-the-Art



# Walking Robots



# Walking Robots



# 2016 Maritime RobotX Challenge



# CanSat/ARLISS



- **A Rocket Launch for International Student Satellites**
- Held in fall in Black Rock, NV
- Two classes of competition
- Many more Japanese than American teams



# The Black Rock Desert



# The Launch



# CanSat Class



- Size and weight of 12oz. beverage can
- Launched to  $\approx 12,000$  ft.
- Options:
  - *Mission* – Do something cool with the payload
  - *Comeback* – Autonomously navigate to target location

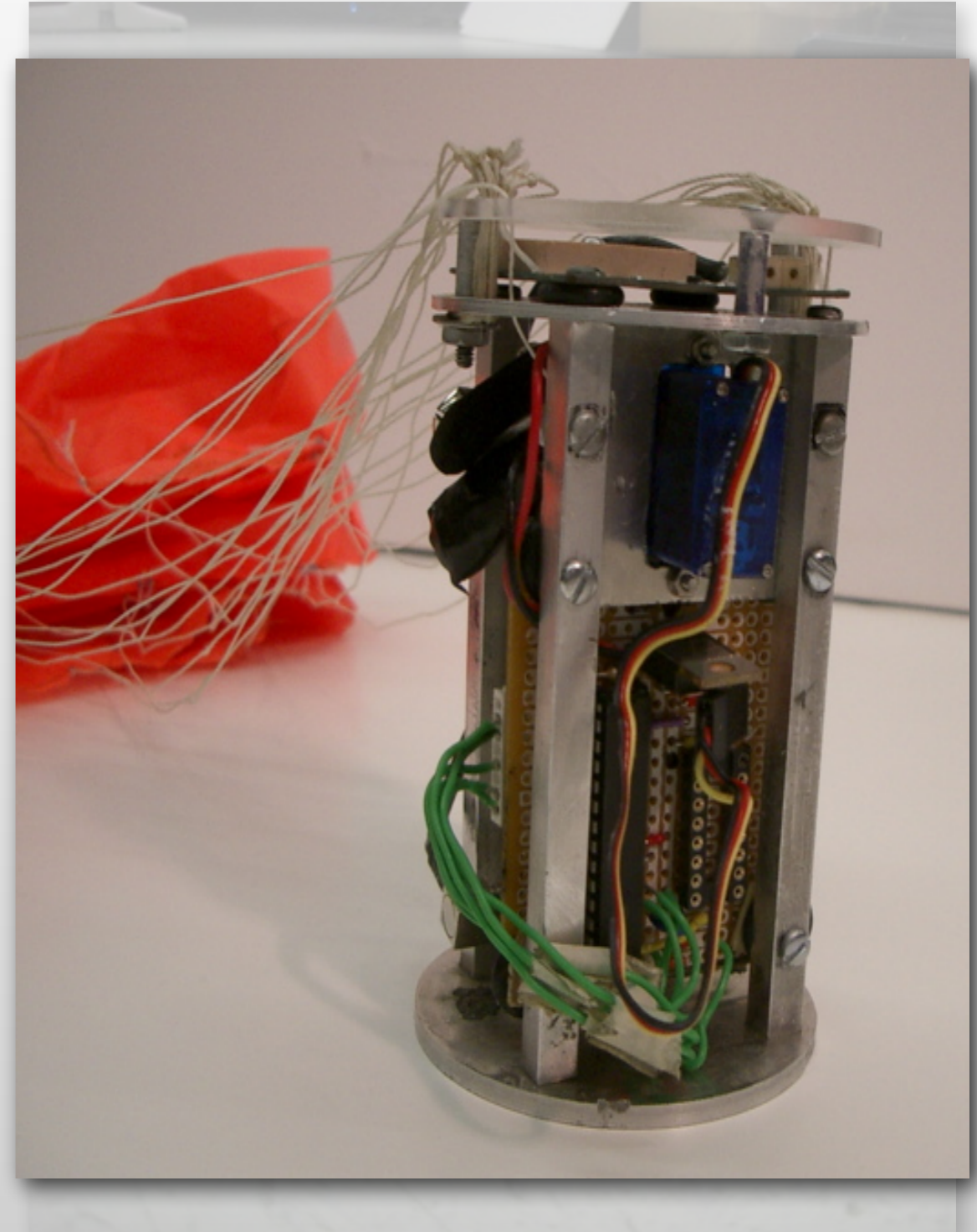




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# Open Class Comeback



- Must fit in 146mm diameter, 240mm deep cylinder and be less than 1050g
- Autonomously navigate to target
- Launched to  $\approx 12,000$  ft.



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# Open Class Examples



# Open Class Examples



# Open Class Examples



# For High School Teams



- CanSAT-sized Mission Class entry
- Same microcontroller as MCHE201 kit
- Possible/likely inclusions:
  - Accelerometers
  - Barometric Pressure/Altitude
  - GPS
  - Camera



# 2015 Launches



- Launch 1 – <https://vimeo.com/docvaughan/arliss2015launch1>
- Launch 2 – <https://vimeo.com/docvaughan/arliss2015launch2>



# Testing on the desert



- Pre-launch – <https://vimeo.com/docvaughan/2015prelaunchtesting>
- Post-launch – <https://vimeo.com/docvaughan/postlaunchtest2015>

# flickr Albums from Past Teams



- 2014 – <https://flic.kr/s/aHsk2LRZYC>
- 2015 – <https://flic.kr/s/aHsk6Xt1hc>
- 2016 – <https://flic.kr/s/aHskC3FrAj>
- 2017 – <https://flic.kr/s/aHskQREGFS>
- 2018 – <https://flic.kr/s/aHsmorEUtX>



# **MCHE 201: Intro. to Eng. Design Robotics Contest Spring 2019**

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# In Fall 2013...



A MCHE470 special topics class on robotics kick-started...

# The Master Plan Contest



UNIVERSITY  
OF  
LOUISIANA  
*L a f a y e t t e*™

Mechanical Engineering  
Robotics Competition

# In Spring 2015...



# Plan

# LA FAYETTE 出行



our people.

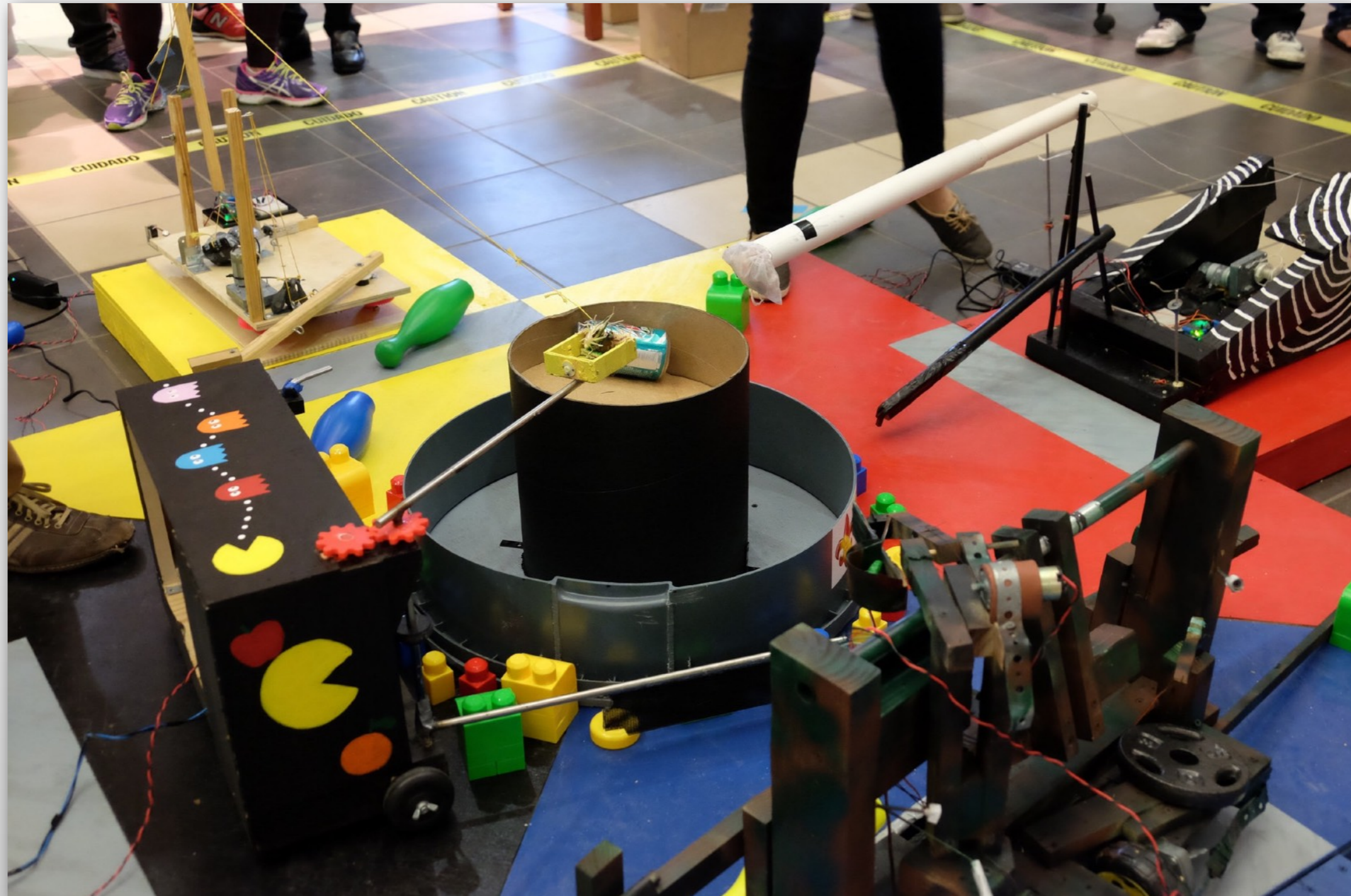
our community.

our economy.

# In Fall 2015...



MCHE201 Teams helped James Bond defeat Blofeld and SPECTRE, saving the world...



# In Spring 2016...



... with the world safe, people are again free to enjoy arts and entertainment.

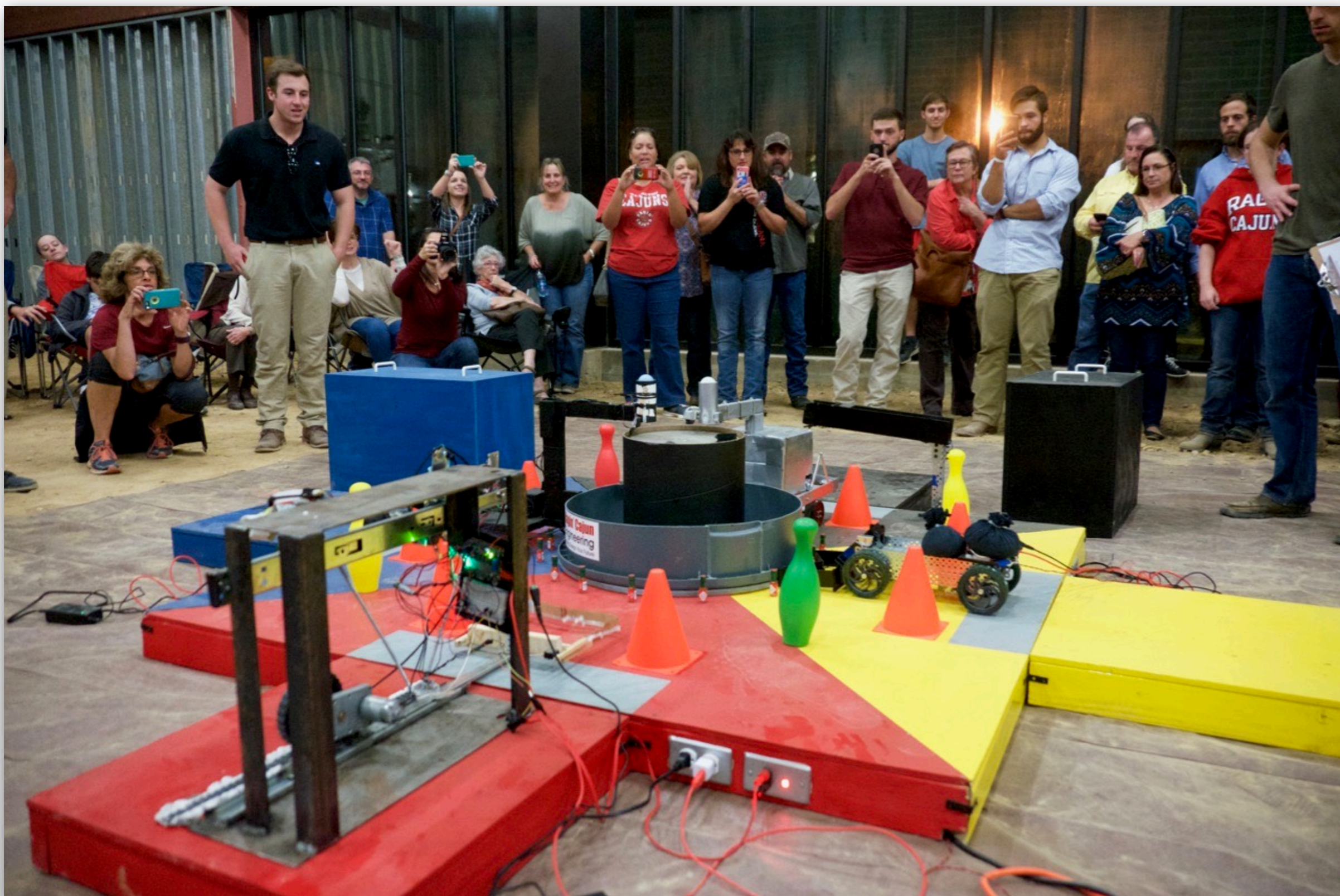




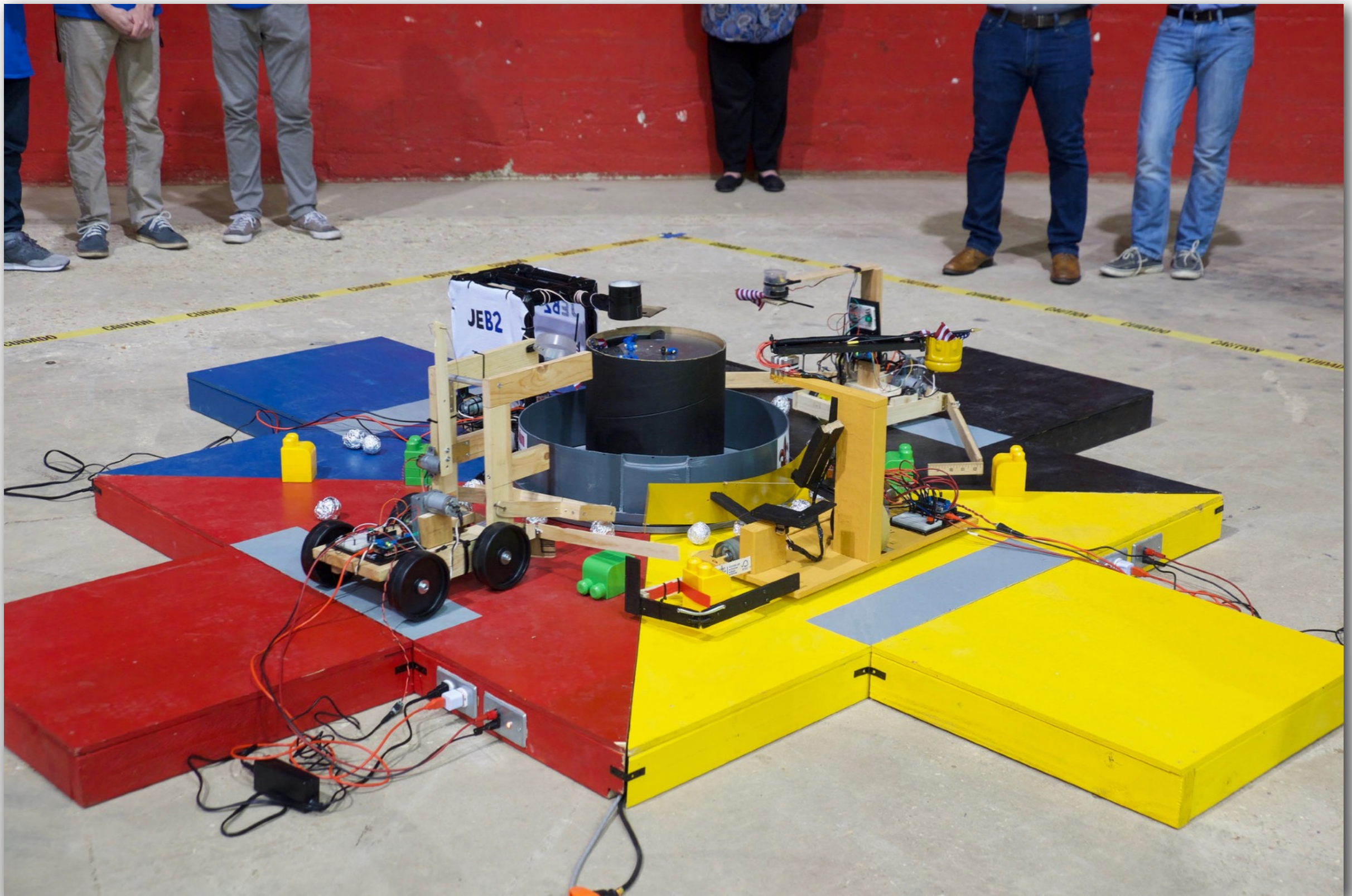
# Festival International de Louisiane



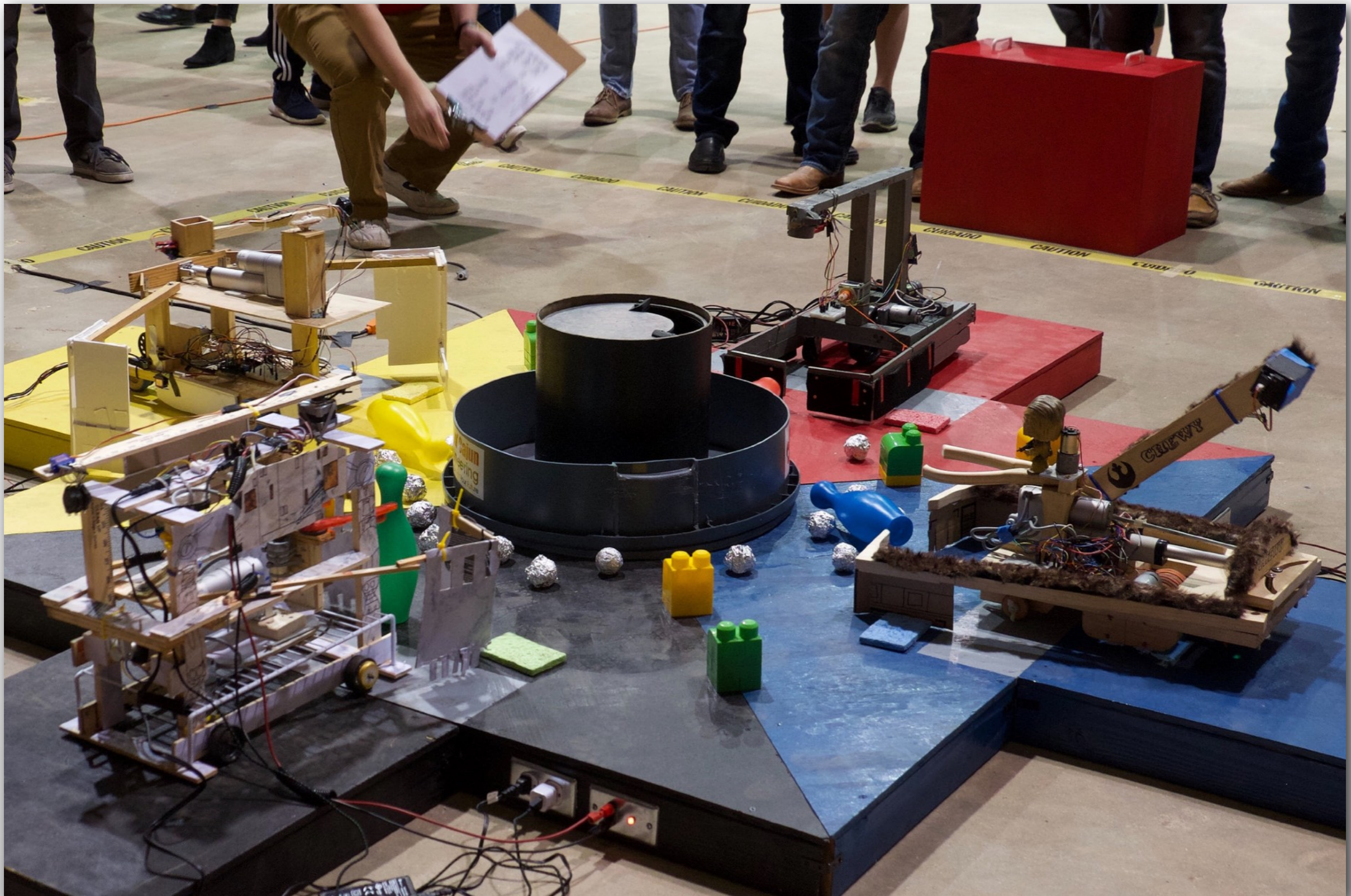
# In Fall 2016... RobotX



# In Spring 2017... Mission to Mars



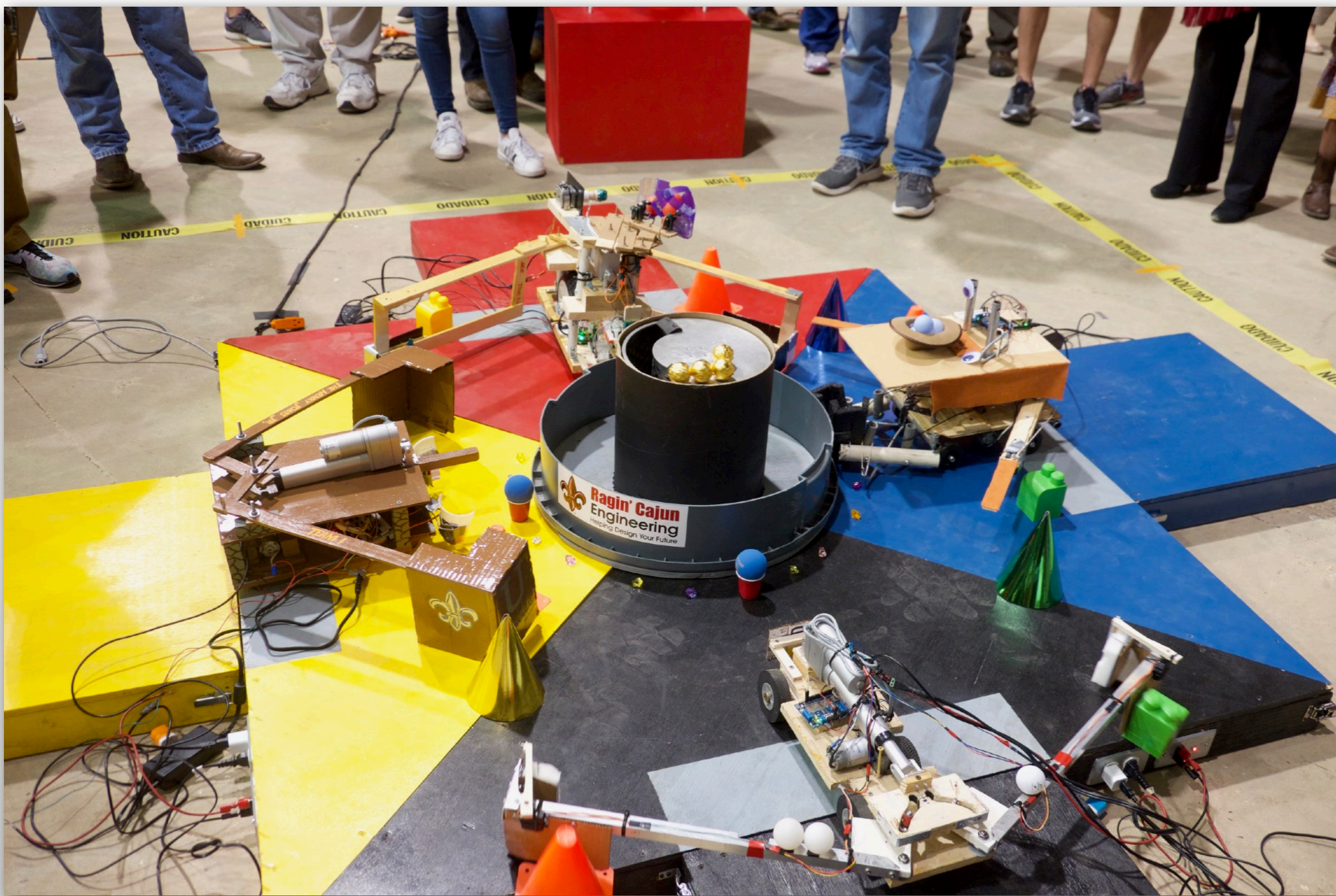
# In Fall 2017...**STAR WARS**



# In Spring 2018... Black Panther



# In Fall 2018... Indiana Jones



# In Spring 2019...



???

# More Details



- Must operate autonomously
- Can use:
  - 1 pyboard microcontroller
  - Components from 3 kits
  - Gravity
  - MCHE201 kit
- Will need to sense a “start” signal from the track
- Teams can buy <\$100 of additional
  - Sensors
  - Building materials
- Must fit onto 2ft-by-2ft starting area and <12"x24"x18"



# Size Requirements



- Your device must be “boxed” prior to each run
- After “boxing” you can only move your device into its final position. You may *not* make *any* other adjustments.
- If adjustments are made, you must re-box your machine (even just reaching inside may warrant this)



# Even More Details



- Machines cannot:
  - Use energy other than that from gravity or the components in the kit
  - Wantonly damage other machines
  - Damage the competition track
  - Damage any competition pieces
  - Operate for more than 30sec.
- Teams cannot:
  - Enter the competition track during a match
  - Interfere with your machine during a match
  - Use foul language during a match

**Any one of  
these will  
result in a DQ**

# Final Competition



- *Tentatively* Thursday, April 25 at Blackham Coliseum
  - Design Review - 5:00pm
  - Robotics Contest - 6:15pm
- Family, friends, UL faculty/staff, high school robotics teams, and industry sponsors attend
- Official National Robotics Week Event



# Design Review



- “Science Fair-style” presentation to:
  - Faculty/staff
  - Graduate students
  - Local robotics clubs
  - Industry guests
- Judged on:
  - Aesthetics
  - Ingenuity
  - Presentation



# Robotics Contest

